



## A parametric Bayesian combination of local and regional information in flood frequency analysis

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[1] Because of their impact on hydraulic structure design as well as on floodplain management, flood quantiles must be estimated with the highest precision given available information. If the site of interest has been monitored for a sufficiently long period (more than 30–40 years), at-site frequency analysis can be used to estimate flood quantiles with a fair precision. Otherwise, regional estimation may be used to mitigate the lack of data, but local information is then ignored. A commonly used approach to combine at-site and regional information is the linear empirical Bayes estimation: Under the assumption that both local and regional flood quantile estimators have a normal distribution, the empirical Bayesian estimator of the true quantile is the weighted average of both estimations. The weighting factor for each estimator is conversely proportional to its variance. We propose in this paper an alternative Bayesian method for combining local and regional information which provides the full probability density of quantiles and parameters. The application of the method is made with the generalized extreme values (GEV) distribution, but it can be extended to other types of extreme value distributions. In this method the prior distributions are obtained using a regional log linear regression model, and then local observations are used within a Markov chain Monte Carlo algorithm to infer the posterior distributions of parameters and quantiles. Unlike the empirical Bayesian approach the proposed method works even with a single local observation. It also relaxes the hypothesis of normality of the local quantiles probability distribution. The performance of the proposed methodology is compared to that of local, regional, and empirical Bayes estimators on three generated regional data sets with different statistical characteristics. The results show that (1) when the regional log linear model is unbiased, the proposed method gives better estimations of the GEV quantiles and parameters than the local, regional, and empirical Bayes estimators; (2) even when the regional log linear model displays a severe relative bias when estimating the quantiles, the proposed method still gives the best estimation of the GEV shape parameter and outperforms the other approaches on higher quantiles provided the relative bias is the same for all quantiles; and (3) the gain in performance with the new approach is considerable for sites with very short records.

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### 1. Introduction

[2] Depending of the availability of data, flood quantiles can be estimated using local frequency analysis, regional frequency analysis or a combination of both. Much effort have been spent during the last decades on the study of the statistical properties of flood distributions, but the lack of sufficiently long data series continues to limit the precision of the results [Bobée and Rasmussen, 1995]. The regionalization concept, introduced by Dalrymple [1960], allows us to mitigate the lack of data by transposing information from gauged sites toward ungauged sites of interest. The

concept was continuously developed since, and new approaches were regularly developed by researchers [e.g., Benson, 1962; Matalas and Gilroy, 1968; Vicens et al., 1975; Rousselle and Hindie, 1976; National Environment Research Council (NERC), 1975; Tasker, 1980; Greiss and Wood, 1981; Kuczera, 1982; Hosking et al., 1985; Lettenmaier et al., 1987; Stedinger and Lu, 1995; Madsen et al., 1994, 1995; Madsen and Rojsberg, 1997; Fill and Stedinger, 1998; Burn, 1990; Groupe de recherche en hydrologie statistique (GREHYS), 1996a, 1996b; Ouarda et al., 2000, 2001; Chokmani and Ouarda, 2004]. Regionalization also results in more precise estimates of quantiles and parameters in sites with short records. It is however difficult to decide whether the local data series are long enough to discard regional information. To deal with this issue, Matalas and Gilroy [1968] recommend choosing the estimator that has the smallest variance. It would however make more sense to combine systematically all available and relevant

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information to have a better knowledge of the hydrological quantities to be estimated. Attention should be paid to the fact that, in a highly heterogeneous region, the addition of the regional information may be counterproductive.

[3] We present in this paper a parametric Bayesian method for combining local and regional information for the GEV distribution. In this method, the prior information is specified from the regional data by the probability distribution of a quantile and two quantile differences  $q_{T1}$ ,  $q_{T2} - q_{T1}$ ,  $q_{T3} - q_{T2}$  (where  $q_T$  is the T-year annual flood quantile). Guidelines for its extension to other extreme value distributions are also provided.

[4] The paper is divided into six parts. Section 2 presents a literature review on the Bayesian approaches for combining local and regional information. In section 3 the proposed Bayesian model is presented and the approaches for regional estimation and for prior specification are developed. The MCMC algorithm that was used to make inference on parameters and quantiles is also presented. The validation methodology is presented in section 4. The case study is presented in section 5, and the results are discussed in section 6. A conclusion is finally presented in section 7.

## 2. Literature Review

[5] The need to combine regional and local information was perceived early and several authors tried to address the issue using various approaches. These approaches can be classified in two groups: (1) mixed approaches which consist in estimating some parameters with the local data and the others with the regional data and (2) approaches that simultaneously use both information sources to estimate all parameters and quantiles. A Bayesian approach can be used in both cases, but to the knowledge of the authors, all approaches that are classified in group 2 are Bayesian. Bayesian approaches can consist either in the construction of an empirical estimator, or the complete inference of the posterior distributions. Depending on the distributions of local and regional estimators, the parametric Bayesian inference can be conducted either analytically or numerically.

### 2.1. Mixed Approaches

[6] The index flood method [Dalrymple, 1960; NERC, 1975] represents a mixed approach when it is applied to a gauged site because the average at-site flow is estimated with local data, while the parameters of the distribution of the normalized quantile are estimated with the regional data. Lettenmaier et al. [1987] used Monte Carlo simulation to show that, if the underlying regional distribution in the index flood approach is the generalized extreme value distribution (GEV), and if the parameters of this distribution are estimated with the L moments or the probability weighted moments (PWM), then the index flood regional estimation is more effective than the local estimation even in case of moderate regional heterogeneity.

[7] Another example of a mixed approach is the "two parameter" GEV/PWM method in which the shape parameter of the GEV distribution is estimated by a regional approach and the two other parameters with the local data. This method showed to be superior to the three parameter GEV/PWM regional index flood method for the estimation of the 100-year flood when the size of local data series

increases, or when the regional heterogeneity is significant [Lettenmaier et al., 1987; Stedinger and Lu, 1995; Fill and Stedinger, 1998].

[8] The procedure recommended by the *Interagency Advisory Committee on Water Data* [1982] is also a mixed approach since it uses a weighted skew (shape of the LP3 distribution) in order to improve the at-site estimator. The weighted skew may be computed through regression analysis, with the at-site skew.

[9] More recently, regional flood frequency analysis using canonical correlation analysis (CCA) has been extended to account for local data in neighborhood delineation [Ouarda et al., 2001]. CCA is a multivariate statistical technique which is used to express hydrological and physiographical variables in two special canonical spaces with special intercorrelation features. Distance in the hydrological space allows the delineation of the neighborhood of a given station using the approach of confidence level ellipsoid [GREHYS, 1996a, 1996b; Ouarda et al. 2000; Girard et al., 2000]. Short local data series can then be helpful to position a station in the hydrological space, and thus to define a more adequate neighborhood. It is a mixed approach to regionalization in the sense that local data influence parameter estimation through the identification of neighborhood limits. A mixed approach can also be Bayesian: for instance, a Bayesian approach was used by Reis et al. [2003, 2005] to infer the skew coefficient of the LP3 distribution while using local data to compute the two other parameters.

### 2.2. Simultaneous Estimation Using Bayesian Approaches

[10] In the Bayesian framework (which will be presented in more detail in section 3), the prior knowledge on the unknown quantities (parameters or quantiles of the local distribution) is described by probability densities. In the hydrological literature dealing with the combination of local and regional information, these prior probability densities are usually obtained from a regional analysis [e.g., Vicens et al., 1975; Madsen and Rojsberg, 1997; Fill and Stedinger, 1998]. The prior probability distributions are then used with the local observations to infer posterior distributions using the Bayes theorem.

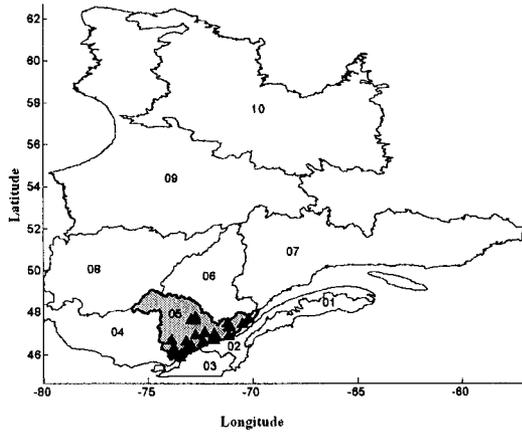
#### 2.2.1. Empirical Bayes Approach

[11] When the probability distributions of both regional and local quantile estimators are normal, it is easily shown [e.g., GREHYS, 1996b] that the quantile posterior distribution is normal with the following parameters:

$$E(q_T | \hat{q}_T^{(L)}, \hat{q}_T^{(R)}) = \frac{\sigma_R^2 \hat{q}_T^{(L)} + \sigma_L^2 \hat{q}_T^{(R)}}{\sigma_R^2 + \sigma_L^2} \quad (1)$$

$$\text{Var}(\hat{q}_T^{(L)}, \hat{q}_T^{(R)}) = \frac{\sigma_R^2 \sigma_L^2}{\sigma_R^2 + \sigma_L^2} \quad (2)$$

where  $q_T$  is the flood quantile we wish to estimate,  $\hat{q}_T^{(L)}$  ( $\hat{q}_T^{(R)}$ ) the local (regional) estimation of  $q_T$ , and  $\sigma_L^2$  ( $\sigma_R^2$ ), its local (regional) estimation variance. The estimator presented in equation (1) is also called linear empirical Bayes estimator and was used by Vicens et al. [1975],



**Figure 1.** Hydrographic regions in the province of Quebec and hydrometric stations of the region 05.

Kuczera [1982], Fill and Stedinger [1998], and Madsen and Rojsberg [1997].

[12] Vicens et al. [1975] assumed that the annual mean flows of New England rivers could be described by a normal distribution and obtained the average and the variance of the prior distribution of the mean annual flows with a multiple linear regression on physiographic variables. They then discussed the variation of the shape of the posterior distributions of flows with respect to the precision of the local and regional distributions. This analysis showed that the combination of the two sources of information reduced the estimation variance of the parameters and that of the mean annual flow. The posterior distribution of streamflows was dominated by the estimator which had the smallest variance.

[13] Kuczera [1982] used an empirical Bayesian method to stabilize the estimation of the variance of flood records, which were assumed to have a lognormal distribution. He obtained the prior information by fitting a gamma distribution to the estimated local variances. He used this model on a simulated data set without intersite

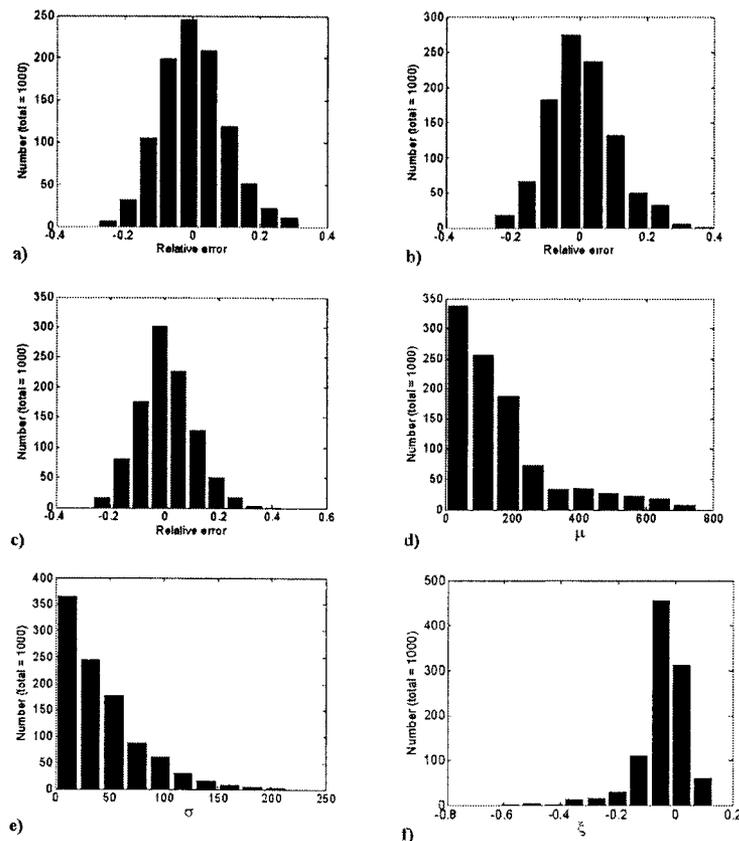
correlation and showed that the relative root mean square error (RRMSE) of the estimated 100-year flood is reduced. The reduction becomes however less important as the regional heterogeneousness increases. Kuczera's [1982] approach was later shown to be sensitive to violations of distributional assumptions [Lettenmaier and Potter, 1995]. The computation of the RRMSE by Kuczera [1982] was possible only because the true values of the quantiles of the simulated flood data were known. In a second application, Kuczera [1982] used real data from selected New England basins. Since the true values of the quantiles were not available, he was only able to show that the combination of the regional and local information stabilizes the estimation of quantiles, i.e., the posterior distribution of quantiles has a smaller variance.

[14] Fill and Stedinger [1998] used the empirical Bayesian method to combine the result of normalized quantiles regression (NQR) with the two-parameter GEV/PWM regional estimator. The NQR method, introduced by Koenker and Bassett [1978] and applied in hydrology by Stedinger [1989], consists in estimating the normalized quantile (the flood quantile divided by the average at-site flow) by linear regression on physiographic variables. Fill and Stedinger [1998] showed by simulation that the empirical Bayesian estimator was more robust and, in terms of root mean square error, performs as well or better than the NQR method or the two-parameter GEV/PWM method.

[15] Madsen and Rojsberg [1997] used two Bayesian estimators of the T-year event in a study that was conducted on flood data from New Zealand. They used the index flood approach for regional estimation and the generalized Pareto distribution (GP) as the distribution of flood peaks above a given threshold. The first estimator is the empirical Bayesian estimator given in equation (1) whereas the second is the mean of the posterior distribution of the quantile obtained with a parametric Bayesian approach. In both cases, the prior information about the parameters of the GP was obtained by linear regression on physiographic variables, and then used to calculate the quantile estimation. Their results indicated that the parametric Bayesian estimator leads to posterior quantile estimation and variance that are

**Table 1.** Characteristics of the Stations of the Hydrographic Region 05 of the Province of Quebec, Canada

Parameter	Mean	Standard Deviation
$q_{10}$ , m <sup>3</sup> /s	243.34	219.26
$q_{100}$ , m <sup>3</sup> /s	333.40	300.83
$q_{1000}$ , m <sup>3</sup> /s	425.09	400.17
Catchment area, km <sup>2</sup>	1114.49	1160.24
Mean slope of the catchment, m/km	2.88	1.01
Percentage of the area covered by lakes, %	3.27	2.48
Mean annual solid and liquid precipitation, mm	1182.84	217.62
Average annual accumulation of degree-days below zero	1481.29	173.99
Matrix of regression parameters (including the intercept parameter)	$\begin{pmatrix} -13,802 & -11,850 & -10,494 \\ 0,974 & 0,974 & 0,979 \\ 0,363 & 0,576 & 0,750 \\ 1,127 & 0,618 & 0,179 \\ -0,178 & -0,258 & -0,335 \\ 0,631 & 0,887 & 1,146 \end{pmatrix}$	-



**Figure 2.** Histograms of relative error on quantiles  $q_{10}$ ,  $q_{100}$ , and  $q_{1000}$  and histograms of the GEV parameters at target sites for the first set of regions (no bias on quantiles, variance factor of the regional regression equal to 10%): (a)  $q_{10}$ , (b)  $q_{100}$ , (c)  $q_{1000}$ , (d)  $\mu$ , (e)  $\sigma$ , and (f)  $\xi$ .

respectively 5% and 11% higher than those obtained with the empirical Bayesian approach. They explained this result with the positive asymmetry introduced by the choice of the prior distribution.

### 2.2.2. Parametric Bayesian Approaches

[16] Less often used because of its complexity, the parametric (or fully) Bayesian inference for nonnormal distributions consists in inferring the posterior probability density of the parameters and the quantiles and generally leads to numerical integration. A common approach to avoid or reduce numerical integration consists in attributing to both local and regional estimators mutually compatible probability distributions (called conjugate distributions) so that the posterior of the unknown quantities distribution can be written in a closed analytical form.

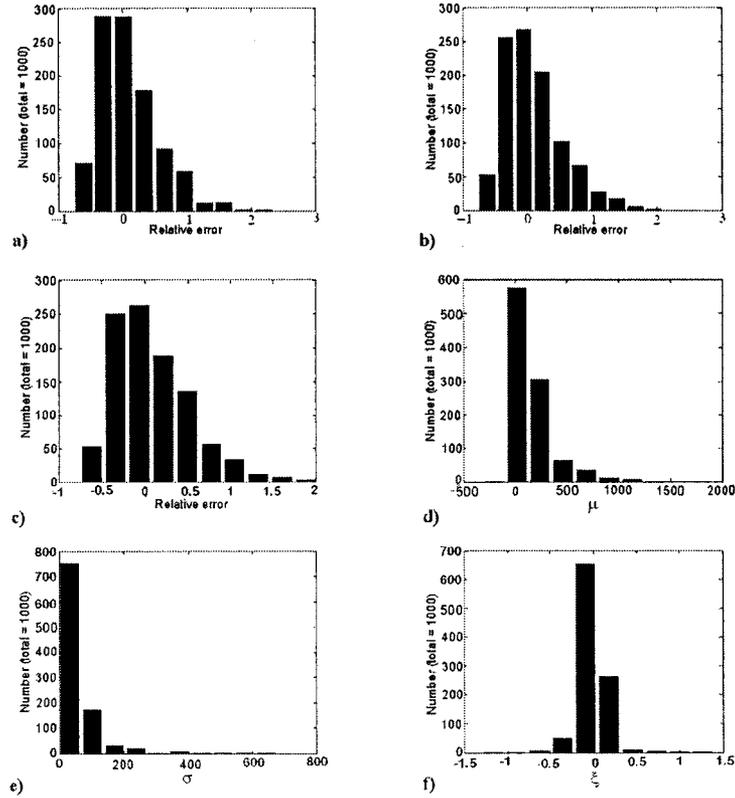
[17] Parametric Bayesian approaches to regionalization were used by *Shane and Gaver* [1970], *Rousselle and Hindie* [1976], *Rasmussen and Rojsberg* [1991], *Madsen et al.* [1994, 1995], and *Madsen and Rojsberg* [1997] for PDS models for which the exceedances are assumed to have a generalized Pareto or an exponential distribution.

[18] *Shane and Gaver* [1970] assumed that the exceedances above a given threshold follow an exponential distribution. They derived the equivalents of equations (1) and (2) for this distribution while searching

for the linear combination of regional and local estimations which gives the smallest root mean square error. They also considered a Bayesian approach where the prior information about the parameter of the exponential distribution describing the magnitude of exceedances is represented by a Gamma distribution. The mean and variance of the prior distribution were obtained by regional multiple linear regression. *Shane and Gaver* [1970] then compared the implication of both estimators on the optimal height of a protection dike and found that both methods give essentially the same result.

[19] *Rousselle and Hindie* [1976] and *Rasmussen and Rojsberg* [1991] considered the classical PDS model with exponentially distributed exceedances and derived the posterior distribution of the T-year event. *Rousselle and Hindie* [1976] considered an informative gamma prior distribution for all the parameters while *Rasmussen and Rojsberg* [1991] assumed a non informative prior for the parameter of the exponential distribution of exceedances.

[20] *Madsen et al.* [1994, 1995] generalized the model of *Rasmussen and Rojsberg* [1991] to the case where the distribution of the exceedances is the Generalized Pareto distribution and applied it to extreme rainfalls. The model of *Madsen et al.* [1994, 1995] was later adapted to index



**Figure 3.** Histograms of relative error on quantiles  $q_{10}$ ,  $q_{100}$ , and  $q_{1000}$  and histograms of the GEV parameters at target sites for the second simulated set of regions (no bias on quantiles, variance factor of the regional regression equal to 50%): (a)  $q_{10}$ , (b)  $q_{100}$ , (c)  $q_{1000}$ , (d)  $\mu$ , (e)  $\sigma$ , and (f)  $\xi$ .

flood regional estimation in the work by *Madsen and Rojsberg* [1997] which was described in section 2.2.1.

### 3. Bayesian Estimation

[21] In the Bayesian approach, the imperfect knowledge of the exact parameter values is accounted for through probability distributions. As stated by *Jaynes* [1985], the width of these probability distributions should be seen rather as a representation of the range of values that are consistent with observed data and the knowledge than as indicators of the range of variability of the parameter. The specification of prior information requires that belief or knowledge about the parameters is expressed in terms of a prior distribution, which must be formulated independently of the observations. This probability density is then used with the observations to obtain the posterior distribution using the well known Bayes theorem:

$$p(\theta|\mathbf{x}) = \frac{f(\mathbf{x}|\theta)\pi(\theta)}{\int f(\mathbf{x}|\theta)\pi(\theta)d(\theta)} \quad (3)$$

where  $\mathbf{x} = (x_1, x_2, \dots, x_n)$  is the vector of observations,  $\pi(\theta)$  the prior probability density of the parameters,  $f(\mathbf{x}|\theta)$  the likelihood of the observations, and  $p(\theta|\mathbf{x})$  the posterior probability density of the parameters given the observations. The posterior distribution is obtained either analytically or numerically using sophisticated techniques such as Markov

chain Monte Carlo (MCMC) algorithms [e.g., *Gilks et al.*, 1996]. Example studies using Bayesian methodologies with the GEV distributions are those by *Coles and Powell* [1996], *Coles and Tawn* [1996], or *Huerta and Sansü* [2005].

[22] In our application,  $\theta = (\mu, \sigma, \xi)$  where  $\mu$ ,  $\sigma$  and  $\xi$  are respectively the position, scale and shape parameters of the GEV distribution. The PDF of the GEV distribution is given by

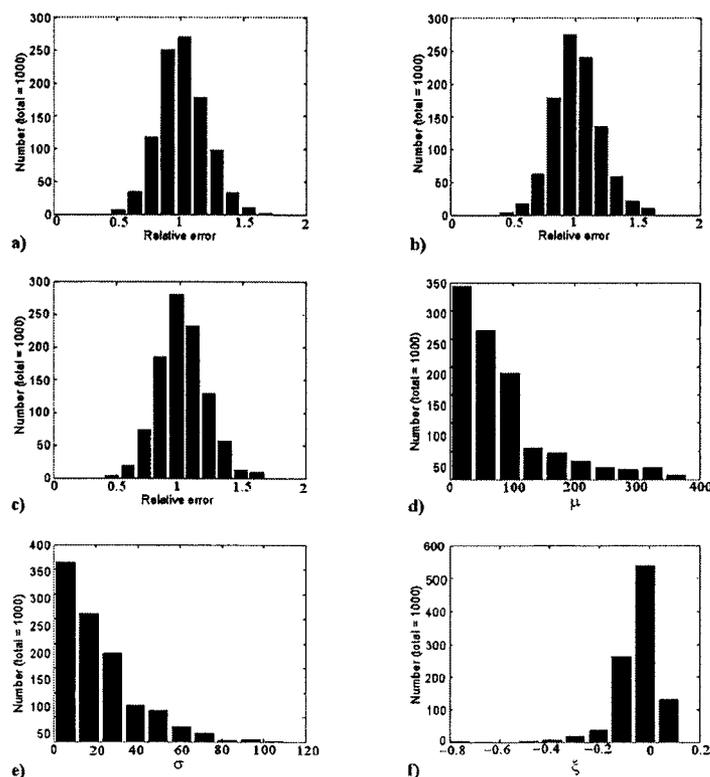
$$f(x_i; \theta) = \frac{1}{\sigma} \left(1 + \xi \left(\frac{x_i - \mu}{\sigma}\right)\right)^{-\frac{\xi+1}{\xi}} \exp\left\{-\left(1 + \xi \left(\frac{x_i - \mu}{\sigma}\right)\right)^{-\frac{1}{\xi}}\right\} \quad (4)$$

Its CDF is given by

$$F(x_i; \theta) = \exp\left(-\left(1 + \xi \frac{x_i - \mu}{\sigma}\right)^{-\frac{1}{\xi}}\right) \quad (5)$$

The quantiles are given by

$$q_T = \mu + \sigma \frac{\left(-\log\left(1 - \frac{1}{T}\right)\right)^{-\xi} - 1}{\xi} \quad (6)$$



**Figure 4.** Histograms of relative error on quantiles  $q_{10}$ ,  $q_{100}$ , and  $q_{1000}$  and histograms of the GEV parameters at target sites for the third simulated set of regions (100% positive relative bias on quantiles, variance factor of the regional regression equal to 10%): (a)  $q_{10}$ , (b)  $q_{100}$ , (c)  $q_{1000}$ , (d)  $\mu$ , (e)  $\sigma$ , and (f)  $\xi$ .

Because the observations are independent, the likelihood of an observed sample  $\mathbf{x} = (x_1, x_2, \dots, x_n)$  is given by

$$L_n(\mathbf{x}; \theta) = \prod_{i=1}^n f(x_i; \theta) \quad (7)$$

The specification of the prior information via  $\pi(\theta)$  can be made in several manners, for example, (1) by attributing a probability distribution to the ratios  $\frac{T_2}{T_3}$  and  $\frac{T_1}{T_2}$  given the quantiles  $q_{T_1}$ ,  $q_{T_2}$  and  $q_{T_3}$  [Crowder, 1992], (2) by specifying the joint distribution of the parameters  $\xi$ ,  $\mu$  and  $\sigma$  [Coles and Powell, 1996], and (3) by using a quantile and two differences of quantiles (e.g.,  $q_{T_3} - q_{T_2}$ ,  $q_{T_2} - q_{T_1}$  and  $q_{T_1}$ ) to which we attribute a probability distribution [Coles and Tawn, 1996; A. Stephenson and M. Ribatet, A user's guide to the evdbayes package (version 1.1), the Comprehensive R Archive Network, <http://cran.r-project.org/>, hereafter referred to as Stephenson and Ribatet, evdbayes user's guide, 2006].

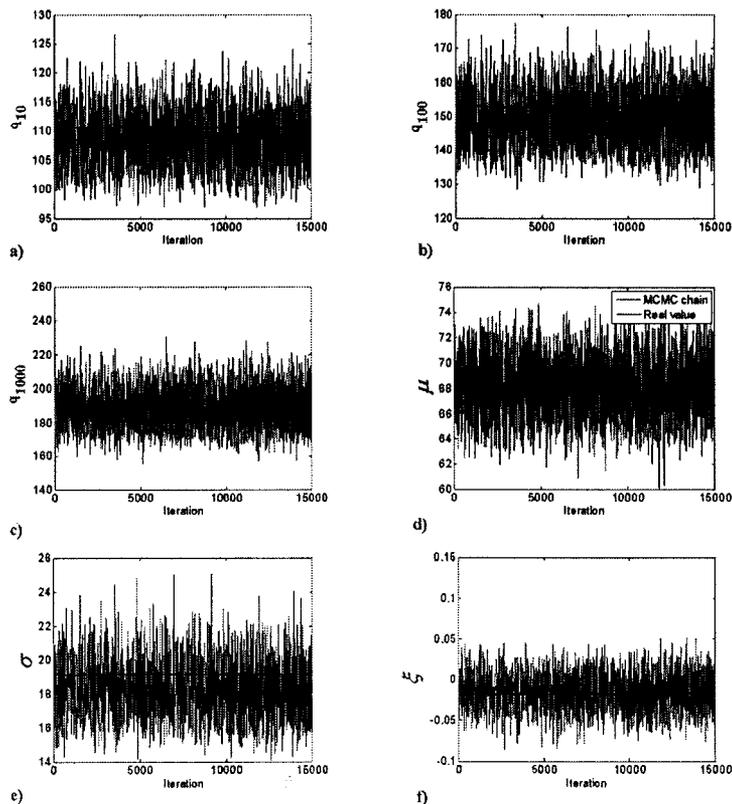
[23] The last method was selected in this study because of its simplicity, and ease of implementation since  $q_{T_3} - q_{T_2}$ ,  $q_{T_2} - q_{T_1}$  and  $q_{T_1}$  are hydrological quantities readily obtained using regional multiple linear regression. The estimation of hydrological quantities using multiple linear regression is straightforward. It was used in several studies [e.g., Matalas and Gilroy, 1968; Stedinger and Tasker, 1985; Tasker and

Stedinger, 1989; Thomas and Benson, 1970; GREHYS, 1996a, 1996b; Ouarda et al., 2001] and provides a fitted (normal) distribution for the explained variable. To the knowledge of the authors, there is no published work in the hydrological literature that can orient the choice of a given class of distribution for  $\xi$ ,  $\mu$ ,  $\sigma$  or for quantile ratios. The use of the first two methods would thus involve much more subjective elements than the application of the well known multiple linear regression model. Indeed, the parameters could have been obtained using multiple regression on physiographical variables, but this would have been a naive approach because of the observed interdependence between the GEV parameters (Stephenson and Ribatet, evdbayes user's guide, 2006): increasing  $\xi$  or  $\sigma$  leads to a heavier tailed distribution, so a priori negative correlation between these parameters is expected [Coles and Tawn, 1996]. This interdependence between parameters is taken into account with a fewer hyperparameters when working in the quantile space (Stephenson and Ribatet, evdbayes user's guide, 2006).

[24] In sections 3.1 – 3.3, more details will be provided on the regional model, prior specification with regional information, and the MCMC algorithm used to infer the posterior.

### 3.1. Regional Model

[25] A regional model contains two parts [GREHYS, 1996a]: (1) a method of determination of homogeneous regions and (2) a regional estimation method. Homogeneous



**Figure 5.** Examples of MCMC chains and real values of quantiles and parameters for first region of the first generated data set: (a)  $q_{10}$ , (b)  $q_{100}$ , (c)  $q_{1000}$ , (d)  $\mu$ , (e)  $\sigma$ , and (f)  $\xi$ .

regions are subsets of stations having similar hydrologic behavior. Several methods have been proposed in the hydrological literature to delineate homogeneous regions such as the regions of influence method [Burn, 1990], correspondence analysis and hierarchical ascending classification [GREHYS, 1996a, 1996b], canonical correlation analysis [Cavadias, 1989; Ouarda et al., 2000, 2001], and the L moments method [Hosking and Wallis, 1993]. Regional estimation can be carried out for instance with the index flood method [Dalrymple, 1960] or the direct multiple regression method [Matalas and Gilroy, 1968; Thomas and Benson, 1970].

[26] The notion of similar hydrological behavior (and thus the concept of regional homogeneity) is relatively vague since it depends on what the modeler considers as being the key interactions between hydrological variables. For instance, a region for which the logarithms of quantiles are grossly linear combinations of some physiographical variables is homogeneous from the point of view of the users of the regional log linear multiple regression model, but not necessarily for the users of the index flood regional model for which the similarity of the shape parameter at all sites is essential. The two approaches can thus lead to different conclusions from the same data set.

[27] In this paper, the first definition of homogeneity (linear relation between the logarithm of quantiles and covariates) is considered. This is important for the validation phase which will involve the generation of regional

data sets. To be consistent with the latter choice, the regional estimation method that will be used is direct multiple regression. There will be no need for a regional delineation method in the validation process since the generation algorithm is designed to directly provide hydrological regions with user-defined characteristics.

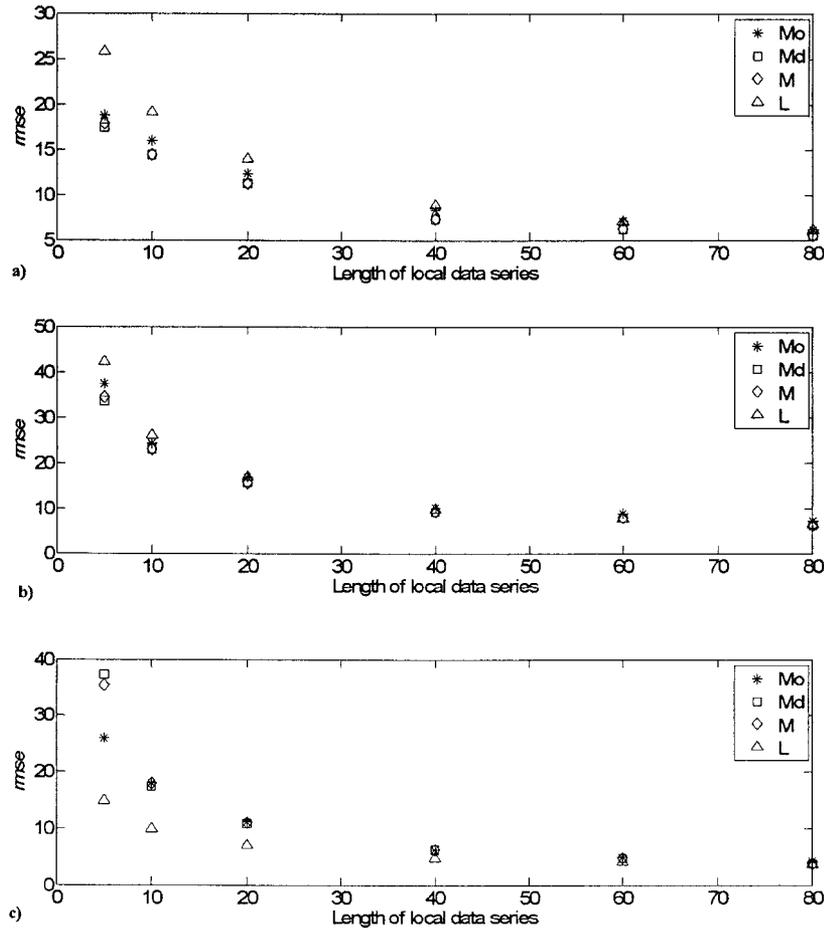
### 3.2. Prior Specification Using the Regional Model

[28] Prior information is specified from the regional model as follows: given three quantiles  $q_{T1}$ ,  $q_{T2}$ ,  $q_{T3}$  such as  $p_1 = \frac{1}{T_1} < p_2 = \frac{1}{T_2} < p_3 = \frac{1}{T_3}$  and their differences  $\Delta q_{T1}$ ,  $\Delta q_{T2}$ ,  $\Delta q_{T3}$  defined by

$$\Delta q_{T1} = q_{T1} = \mu - (-\log(1 - p_1))^{-\xi} \frac{\sigma}{\xi} \quad (8)$$

$$\Delta q_{T2} = q_{T2} - q_{T1} = \left( (-\log(1 - p_2))^{-\xi} - (-\log(1 - p_1))^{-\xi} \right) \frac{\sigma}{\xi} \quad (9)$$

$$\Delta q_{T3} = q_{T3} - q_{T1} = \left( (-\log(1 - p_3))^{-\xi} - (-\log(1 - p_1))^{-\xi} \right) \frac{\sigma}{\xi} \quad (10)$$



**Figure 6.** RMSE of the estimators of  $\mu$  according to the length of local data series: (a) first generated data set, (b) second generated data set, and (c) third generated data set.

The log linear model is used to describe the relationship between the hydrological quantities and physiographic variables. If we denote  $\Delta q_{Ti}^R$  the regional estimation of  $\Delta q_{Ti}$ , the regional regression model is given by

$$\log(\bar{\Delta}q_{Ti}^R) = \begin{bmatrix} \log(\bar{\Delta}q_{T1}^R) \\ \log(\bar{\Delta}q_{T2}^R) \\ \log(\bar{\Delta}q_{T3}^R) \end{bmatrix} = MVN(\mathbf{x}\bar{\beta}, \Sigma) \quad (11)$$

where

$$\mathbf{x} = \begin{bmatrix} 1 \\ A_1 \\ \cdot \\ \cdot \\ A_m \end{bmatrix} \text{ and } \bar{\beta} = \begin{pmatrix} \bar{\beta}^{(1)} \\ \bar{\beta}^{(2)} \\ \bar{\beta}^{(3)} \end{pmatrix}$$

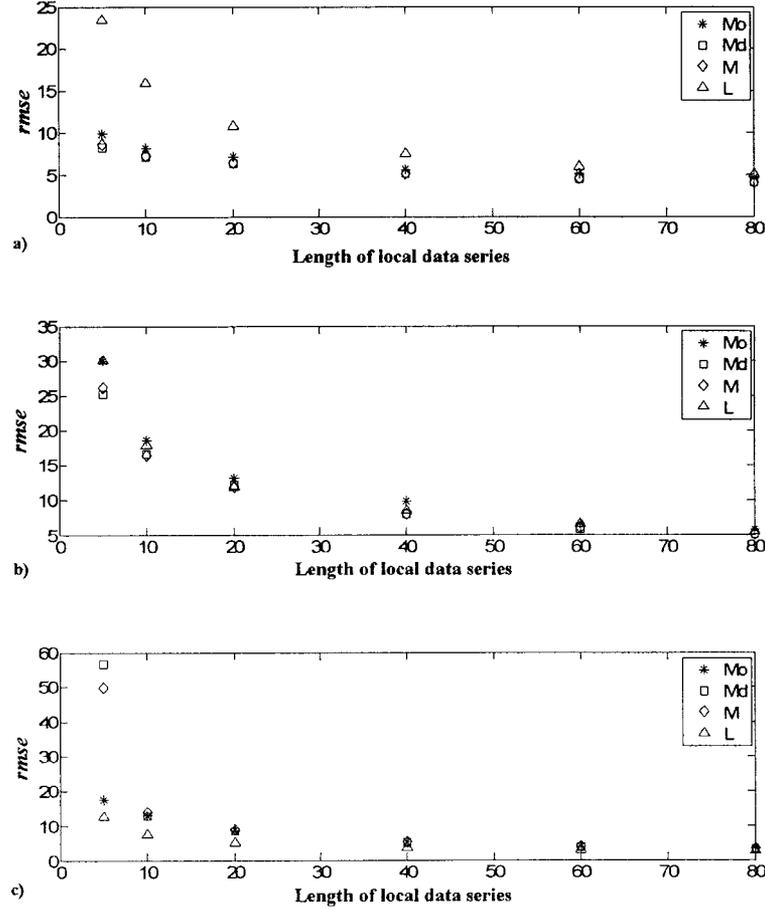
with  $\bar{\beta}^{(i)} = (\bar{\beta}_0^{(i)}, \bar{\beta}_1^{(i)}, \dots, \bar{\beta}_m^{(i)})$ . In equation (11),  $MVN(\mathbf{x}\bar{\beta}, \Sigma)$  stands for the multivariate normal distribution with mean vector  $\mathbf{x}\bar{\beta}$  and variance-covariance matrix  $\Sigma$ .  $A_k$  represents the value of the  $k$ th physiographic or meteorological variable at the site of interest,  $\bar{\beta}_k^{(i)}$  is a

regression coefficient, and  $m$  is the number of physiographic variables.

[29] We assume that the errors in model (11) do not display intersite correlation but that there may be some correlation between the error series corresponding to different quantiles. Model (11) is thus a case of the classical multivariate normal distribution with independent realizations. Its location parameters as well as its variance-covariance matrix can thus be obtained using ordinary least squares. More complex procedures such as generalized least squares [Stedinger and Tasker, 1985, 1986; Tasker and Stedinger, 1989] which account for intersite correlations could have been considered. However, this would have complicated the already difficult simulation of the validation data set (see section 4). Such procedures can improve the precision of the regional model when used on real data and deserve consideration in future work.

[30] Since there is no intersite correlation,  $\bar{\beta}^{(i)}$  is obtained by solving the following equation with the ordinary least squares method (OLS):

$$\log(\Delta q_{Ti}^R) = \mathbf{x}\bar{\beta}^{(i)} + \varepsilon^{(i)}T_i \in \{T_1, T_2, T_3\} \quad (12)$$



**Figure 7.** RMSE of the estimators of  $\sigma$  according to the length of local data series: (a) first generated data set, (b) second generated data set, and (c) third generated data set.

where  $\varepsilon^{(i)}$  is the random error term. The elements of  $\Sigma$  are directly computed from the data:

$$\Sigma_{ij} = \text{cov}(\varepsilon^{(i)}, \varepsilon^{(j)}) \quad (13)$$

[31] We deduce from (11) and (12) that

$$\pi(\mu, \sigma, \xi) \propto J \frac{1}{\Delta q_{T1} \Delta q_{T2} \Delta q_{T3}} \cdot \exp\left(-\frac{(\log(\Delta \mathbf{q}_T) - \tilde{\beta} \mathbf{x})' \Sigma^{-1} (\log(\Delta \mathbf{q}_T) - \tilde{\beta} \mathbf{x})}{2}\right) \quad (14)$$

where  $J$  is the Jacobian of the transformation of  $(\Delta q_{T1}, \Delta q_{T2}, \Delta q_{T3})$  toward  $(\mu, \sigma, \xi)$ . The expression of  $J$  is derived by Stephenson and Ribatet (evdbayes user's guide, 2006):

$$J = \begin{cases} \frac{\sigma}{\xi^2} \left| \sum_{i,j \in \{1,2,3\}; i < j} (-1)^{i+j} (x_i x_j)^{-\xi} \log\left(\frac{x_j}{x_i}\right) \right| & \text{si } \xi > 0 \\ \frac{\sigma}{2} \left| \sum_{i,j \in \{1,2,3\}; i < j} (-1)^{i+j} \log(x_i) \log(x_j) \log\left(\frac{x_j}{x_i}\right) \right| & \text{si } \xi = 0 \end{cases} \quad (15)$$

where  $x_i = -\log(1 - p_i)$ .

[32] For the comparison with the empirical Bayesian estimator,  $E(q_T^R)$  and  $\text{Var}(q_T^R)$  are also estimated from the solutions of the following equation:

$$\log(q_T^R) = \mathbf{x} \beta^{(i)} + \varepsilon^{(i)} \quad (16)$$

The bias introduced by the logarithmic transformation in (16) is also corrected:

$$q_T^R \sim N(b_i^r \exp(\mathbf{x} \beta^{(i)}) + b_i^a, \sigma_{T_i}^R) \quad (17)$$

where  $b_i^r$  and  $b_i^a$  are the relative and absolute biases, and  $\sigma_{T_i}^R$  the quantile estimation variance. The relative and absolute biases are estimated by ordinary least squares using observed values of  $\hat{q}_T$  and those simulated with equation (16).

### 3.3. Inference on Parameters and Quantiles

[33] Inference on parameters and quantiles was carried out with the Metropolis-Hasting algorithm following Stephenson and Ribatet (evdbayes user's guide, 2006). The goal of the Metropolis-Hastings algorithm is to construct a Markov chain for which the equilibrium distribution is the posterior defined in (3). The generic Metropolis-Hasting algorithm can be written as follows.

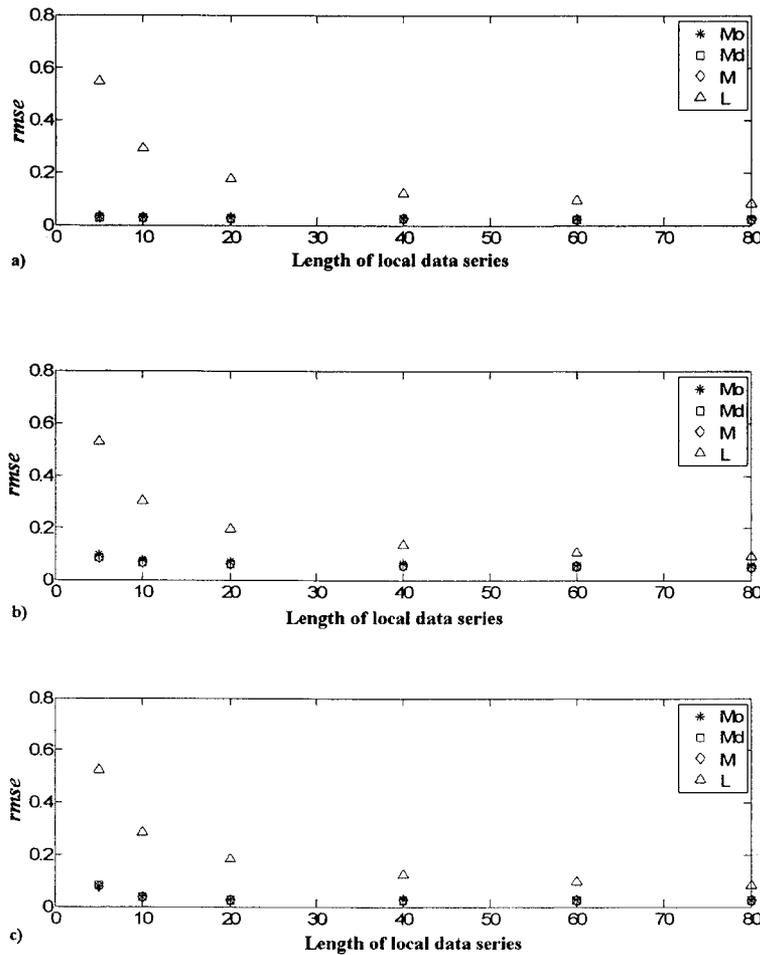


Figure 8. RMSE of the estimators of  $\xi$  according to the length of local data series: (a) first generated data set, (b) second generated data set, and (c) third generated data set.

Table 2. RMSE, Bias, and Standard Deviation of the Estimators of  $\mu$

	l	First Generated Data Set				Second Generated Data Set				Third Generated Data Set			
		M	Md	Mo	L	M	Md	Mo	L	M	Md	Mo	L
RMSE	5	17.86	17.45 <sup>a</sup>	18.76	25.81	34.51	33.50 <sup>a</sup>	37.40	42.27	35.35	37.36	25.93	14.92 <sup>a</sup>
RMSE	10	14.41	14.38 <sup>a</sup>	15.96	19.15	23.04	23.00 <sup>a</sup>	24.30	26.03	17.90	17.38	17.91	10.01 <sup>a</sup>
RMSE	20	11.21	11.21 <sup>a</sup>	12.29	13.96	15.61 <sup>a</sup>	15.66	16.90	16.85	10.96	10.81	11.07	7.05 <sup>a</sup>
RMSE	40	7.33	7.33 <sup>a</sup>	8.32	8.84	9.25 <sup>a</sup>	9.25	10.05	9.82	6.35	6.29	6.30	4.82 <sup>a</sup>
RMSE	60	6.22 <sup>a</sup>	6.23	7.10	7.05	7.84	7.89	8.87	7.74 <sup>a</sup>	4.84	4.80	5.06	4.16 <sup>a</sup>
RMSE	80	5.52	5.49 <sup>a</sup>	6.17	6.12	6.35	6.32 <sup>a</sup>	7.12	6.54	3.90	3.86	4.29	3.64 <sup>a</sup>
Bias	5	0.107 <sup>a</sup>	0.671	1.074	2.891	-0.071 <sup>a</sup>	2.315	2.524	7.528	18.180	17.837	17.421	0.579 <sup>a</sup>
Bias	10	0.694 <sup>a</sup>	0.901	1.488	1.835	1.265 <sup>a</sup>	1.402	1.294	3.336	12.027	11.783	11.292	0.487 <sup>a</sup>
Bias	20	0.632 <sup>a</sup>	0.729	1.023	0.945	0.472	0.419 <sup>a</sup>	0.551	1.375	6.829	6.723	6.431	0.189 <sup>a</sup>
Bias	40	0.183 <sup>a</sup>	0.201	0.323	0.188	-0.056 <sup>a</sup>	-0.084	-0.265	0.522	3.585	3.521	3.259	0.003 <sup>a</sup>
Bias	60	0.050	0.046	-0.116	0.034 <sup>a</sup>	-0.348	-0.386	-0.543	0.022 <sup>a</sup>	2.303	2.260	2.189	-0.078 <sup>a</sup>
Bias	80	0.020	0.021	-0.047	0.003 <sup>a</sup>	-0.032 <sup>a</sup>	-0.047	-0.365	0.240	1.594	1.564	1.508	-0.172 <sup>a</sup>
Standard deviation	5	17.86	17.44 <sup>a</sup>	18.73	25.65	34.51	33.42 <sup>a</sup>	37.31	41.59	30.32	32.83	19.20	14.91 <sup>a</sup>
Standard deviation	10	14.39	14.35 <sup>a</sup>	15.90	19.06	23.00	22.96 <sup>a</sup>	24.27	25.81	13.26	12.77	13.90	10.00 <sup>a</sup>
Standard deviation	20	11.20	11.19 <sup>a</sup>	12.25	13.93	15.60 <sup>a</sup>	15.66	16.90	16.79	8.57	8.47	9.01	7.05 <sup>a</sup>
Standard deviation	40	7.33	7.32 <sup>a</sup>	8.31	8.83	9.25 <sup>a</sup>	9.25	10.05	9.80	5.25	5.21	5.39	4.82 <sup>a</sup>
Standard deviation	60	6.22 <sup>a</sup>	6.23	7.09	7.05	7.83	7.88	8.85	7.74 <sup>a</sup>	4.25	4.24	4.56	4.16 <sup>a</sup>
Standard deviation	80	5.52	5.49 <sup>a</sup>	6.17	6.12	6.35	6.32 <sup>a</sup>	7.11	6.54	3.56	3.53 <sup>a</sup>	4.02	3.64

<sup>a</sup>Smallest value for a given data set and a given length of the local data series.

Table 3. RMSE, Bias, and Standard Deviation of the Estimators of  $\sigma$

	First Generated Data Set				Second Generated Data Set				Third Generated Data Set				
	l	M	Md	Mo	L	M	Md	Mo	L	M	Md	Mo	L
RMSE	5	8.58	8.26 <sup>a</sup>	9.87	23.43	26.21	25.21 <sup>a</sup>	30.08	30.00	49.79	56.73	17.59	12.49 <sup>a</sup>
RMSE	10	7.21	7.09 <sup>a</sup>	8.18	15.89	16.35 <sup>a</sup>	16.62	18.55	17.92	13.89	12.73	12.92	7.50 <sup>a</sup>
RMSE	20	6.36	6.30 <sup>a</sup>	7.12	10.74	11.86	12.09	13.16	11.84 <sup>a</sup>	8.91	8.39	8.59	5.06 <sup>a</sup>
RMSE	40	5.17	5.13 <sup>a</sup>	5.55	7.54	8.01	7.99 <sup>a</sup>	9.85	8.57	5.39	5.15	5.29	3.59 <sup>a</sup>
RMSE	60	4.51	4.50 <sup>a</sup>	5.12	5.92	6.01	5.92 <sup>a</sup>	6.73	6.53	4.02	3.87	3.93	2.95 <sup>a</sup>
RMSE	80	4.03	4.02 <sup>a</sup>	4.58	5.02	5.04	5.02 <sup>a</sup>	5.77	5.46	3.34	3.23	3.50	2.64 <sup>a</sup>
Bias	5	0.859	-0.001 <sup>a</sup>	-0.156	-1.837	1.634 <sup>a</sup>	-3.089	-6.712	-2.185	15.090	14.079	11.899	-1.648 <sup>a</sup>
Bias	10	0.546	-0.015 <sup>a</sup>	-0.255	-0.534	-0.566 <sup>a</sup>	-2.383	-4.056	-1.682	9.840	9.032	8.696	-0.081 <sup>a</sup>
Bias	20	0.381	-0.028 <sup>a</sup>	-0.358	-0.136	-0.622 <sup>a</sup>	-1.505	-1.982	-1.256	6.033	5.610	5.364	-0.146 <sup>a</sup>
Bias	40	0.286	0.018	-0.247	0.005 <sup>a</sup>	0.190	-0.225	-0.152	0.051 <sup>a</sup>	3.372	3.150	3.010	-0.091 <sup>a</sup>
Bias	60	0.178	-0.031	-0.120	0.012 <sup>a</sup>	-0.033 <sup>a</sup>	-0.331	-0.470	-0.121	2.284	2.134	1.920	-0.064 <sup>a</sup>
Bias	80	0.073	-0.085	-0.223	-0.049 <sup>a</sup>	-0.015 <sup>a</sup>	-0.232	-0.148	-0.105	1.797	1.686	1.632	0.020 <sup>a</sup>
Standard deviation	5	8.53	8.26 <sup>a</sup>	9.86	23.35	26.16	25.02 <sup>a</sup>	29.32	29.92	47.45	54.95	12.96	12.39 <sup>a</sup>
Standard deviation	10	7.19	7.09 <sup>a</sup>	8.18	15.88	16.34 <sup>a</sup>	16.45	18.10	17.84	9.80	8.97	9.55	7.50 <sup>a</sup>
Standard deviation	20	6.35	6.30 <sup>a</sup>	7.11	10.74	11.84	12.00	13.01	11.78 <sup>a</sup>	6.56	6.24	6.71	5.05 <sup>a</sup>
Standard deviation	40	5.16	5.13 <sup>a</sup>	5.55	7.54	8.01	7.99 <sup>a</sup>	9.85	8.57	4.20	4.07	4.35	3.59 <sup>a</sup>
Standard deviation	60	4.51	4.50 <sup>a</sup>	5.12	5.92	6.01	5.91 <sup>a</sup>	6.71	6.53	3.31	3.23	3.43	2.95 <sup>a</sup>
Standard deviation	80	4.03	4.02 <sup>a</sup>	4.57	5.02	5.04	5.02 <sup>a</sup>	5.77	5.46	2.81	2.76	3.09	2.64 <sup>a</sup>

<sup>a</sup>Smallest value for a given data set and a given length of the local data series.

1. Start with some initial parameter value  $\theta_0$  and set  $i$  to zero.
2. Given the parameter vector  $\theta_i$ , draw a candidate value  $\theta_{i+1}$  from some proposal distribution.
3. Compute the ratio  $R$  of the posterior density at the candidate and initial points,  $R = P(\theta_{i+1}|\mathbf{x})/P(\theta_i|\mathbf{x})$ .
4. With probability  $\min(R, 1)$ , accept the candidate parameter vector, else set  $\theta_{i+1} = \theta_i$ .
5. Set  $i = i + 1$  and return to step 2.

[34] Many versions of this algorithm have been proposed depending on the proposal distribution and the order in which the parameters are updated. In this study, the three parameters of the GEV distribution are updated successively with normal proposal distributions for  $\mu$ ,  $\log(\sigma)$  and  $\xi$  as proposed by Stephenson and Ribatet (edvbayes user's guide, 2006). The steps to generate the parameters at step  $i + 1$  (i.e  $\mu_{i+1}$ ,  $\sigma_{i+1}$  and  $\xi_{i+1}$ ) given  $\mu_i, \sigma_i$  and  $\xi_i$  are the following.

1. Propose  $\mu^* \sim N(\mu_i, \sigma_\mu)$  where  $N$  represents the normal distribution.
2. Set  $\Delta = \frac{P(\mu^*, \sigma_i, \xi_i|\mathbf{x})}{P(\mu_i, \sigma_i, \xi_i|\mathbf{x})}$ .
3. Set  $\mu_{i+1} = \mu^*$  with probability  $\min\{1, \Delta\}$ , else set  $\mu_{i+1} = \mu_i$ .
4. Propose  $\sigma^* \sim LN(\sigma_i, \sigma_\sigma)$  where  $LN$  represents the lognormal distribution.
5. Set  $\Delta = \frac{P(\mu_i, \sigma^*, \xi_i|\mathbf{x})}{P(\mu_i, \sigma_i, \xi_i|\mathbf{x})}$ .
6. Set  $\sigma_{i+1} = \sigma^*$  with probability  $\min\{1, \Delta\}$ , else set  $\sigma_{i+1} = \sigma_i$ .
7. Propose  $\xi^* \sim N(\xi_i, \sigma_\xi)$ .
8. Set  $\Delta = \frac{P(\mu_i, \sigma_i, \xi^*|\mathbf{x})}{P(\mu_i, \sigma_i, \xi_i|\mathbf{x})}$ .
9. Set  $\xi_{i+1} = \xi^*$  with probability  $\min\{1, \Delta\}$ , else set  $\xi_{i+1} = \xi_i$ .

[35] The variance parameters  $\sigma_\mu$ ,  $\sigma_\sigma$  and  $\sigma_\xi$  of the proposal distributions are tuned using a trial-error method to improve convergence speed and acceptance rates. The Geweke [1992] test was chosen to assess the convergence of the MCMC chain because of its ease of interpretation. It is based on a test of

equality of the means of the first part and the last part of a Markov chain.

#### 4. Validation Methodology

[36] Simulation is an attractive way to validate the proposed methodology of combination of local and regional information. However, generating regional data is not a trivial task. It involves reproducing (1) at-site frequency distributions, (2) the relation between at-site flood features and explanatory physiographical and meteorological variables, (3) the dependence between the various explanatory variables at a given site, (4) the relation between explanatory variables at different sites, and (5) the regional heterogeneity characteristics. Unfortunately, most of these aspects are still not well understood, and even if they were, it would be hard to generate data sets which respect all the above mentioned constraints. Nevertheless, a simulation study was performed in which an effort was made to preserve as much as possible of the elements mentioned above. This simulation study was performed in four steps: (1) define the data structures to be generated, (2) set up a generation procedure which respects the maximum of above mentioned constraints, (3) generate the data sets, and (4) evaluate the studied parameters and quantile estimation methods on the data sets. All these steps will be described in detail in the following sections.

[37] It is obvious that the performance of the combination method will be influenced by the size of local data series as well as the bias and precision of the regional model. Another intuitive factor is the number of stations within the region, but its effects are not direct: it plays a role through its linkage with the bias and precision of the regional model. For this reason, several cases were considered in the validation study, corresponding to different values of the bias and precision of the regional model. For each of these cases, the performance of the studied combination methodology were assessed for different lengths of the local data series. The data structure for each

**Table 4.** RMSE, Bias, and Standard Deviation of the Estimators of  $\xi$

	l	First Generated Data Set				Second Generated Data Set				Third Generated Data Set			
		M	Md	Mo	L	M	Md	Mo	L	M	Md	Mo	L
RMSE	5	2.91E-2	2.90E-2 <sup>a</sup>	3.31E-2	54.78E-2	8.66E-2	8.54E-2 <sup>a</sup>	9.63E-2	53.17E-2	7.82E-2	8.44E-2	7.63E-2 <sup>a</sup>	52.60E-2
RMSE	10	2.68E-2 <sup>a</sup>	2.69E-2	3.02E-2	29.33E-2	6.96E-2 <sup>a</sup>	6.98E-2	7.81E-2	30.29E-2	3.68E-2 <sup>a</sup>	3.71E-2	3.97E-2	28.71E-2
RMSE	20	2.56E-2 <sup>a</sup>	2.56E-2	2.94E-2	17.54E-2	6.27E-2 <sup>a</sup>	6.28E-2	7.06E-2	19.58E-2	2.39E-2 <sup>a</sup>	2.42E-2	2.75E-2	18.62E-2
RMSE	40	2.37E-2	2.37E-2 <sup>a</sup>	2.76E-2	11.97E-2	5.75E-2 <sup>a</sup>	5.76E-2	6.54E-2	13.56E-2	2.52E-2 <sup>a</sup>	2.55E-2	2.94E-2	12.33E-2
RMSE	60	2.30E-2	2.30E-2 <sup>a</sup>	2.60E-2	9.56E-2	5.38E-2 <sup>a</sup>	5.39E-2	5.79E-2	10.73E-2	2.52E-2 <sup>a</sup>	2.55E-2	2.82E-2	9.77E-2
RMSE	80	2.27E-2	2.27E-2 <sup>a</sup>	2.62E-2	8.20E-2	4.94E-2 <sup>a</sup>	4.95E-2	5.55E-2	9.06E-2	2.48E-2 <sup>a</sup>	2.51E-2	2.85E-2	8.33E-2
Bias	5	-22.18E-04	-14.63E-04	-11.50E-04 <sup>a</sup>	-11.53E-02	33.48E-04 <sup>a</sup>	70.26E-04	1.66E-02	-13.05E-02	-11.77E-04	-8.45E-04 <sup>a</sup>	12.27E-04	-8.73E-02
Bias	10	-16.63E-04	-10.22E-04	34.36E-06 <sup>a</sup>	-4.63E-02	64.55E-04 <sup>a</sup>	86.15E-04	1.41E-02	-4.68E-02	71.20E-04 <sup>a</sup>	78.75E-04	89.57E-04	-3.80E-02
Bias	20	-14.35E-04	-9.81E-04	6.04E-04 <sup>a</sup>	-1.73E-02	73.31E-04 <sup>a</sup>	91.22E-04	1.17E-02	-2.62E-02	1.38E-02	1.42E-02	1.48E-02	-59.28E-04 <sup>a</sup>
Bias	40	-12.21E-04	-9.16E-04	-5.04E-06 <sup>a</sup>	-92.39E-04	49.99E-04 <sup>a</sup>	58.58E-04	76.29E-04	-2.19E-02	1.77E-02	1.80E-02	1.87E-02	21.59E-04 <sup>a</sup>
Bias	60	-14.21E-04	-11.23E-04	-3.27E-04 <sup>a</sup>	-77.59E-04	52.45E-04 <sup>a</sup>	56.00E-04	59.41E-04	-1.35E-02	1.87E-02	1.90E-02	1.93E-02	-1.33E-04 <sup>a</sup>
Bias	80	-12.23E-04	-9.88E-04	-4.65E-04 <sup>a</sup>	-36.89E-04	53.12E-04 <sup>a</sup>	53.23E-04	60.27E-04	-1.02E-02	1.90E-02	1.93E-02	2.08E-02	-3.75E-04 <sup>a</sup>
Standard deviation	5	2.90E-2	2.89E-2 <sup>a</sup>	3.31E-2	53.55E-2	3.31E-2	8.65E-2	8.51E-2 <sup>a</sup>	9.49E-2	51.54E-2	7.82E-2	7.62E-2 <sup>a</sup>	51.87E-2
Standard deviation	10	2.67E-2 <sup>a</sup>	2.68E-2	3.02E-2	28.96E-2	6.93E-2	6.92E-2 <sup>a</sup>	7.68E-2	29.92E-2	3.61E-2 <sup>a</sup>	3.62E-2	3.87E-2	28.46E-2
Standard deviation	20	2.55E-2 <sup>a</sup>	2.56E-2	2.94E-2	17.45E-2	6.22E-2	6.21E-2 <sup>a</sup>	6.96E-2	19.40E-2	1.95E-2 <sup>a</sup>	1.96E-2	2.31E-2	18.61E-2
Standard deviation	40	2.37E-2 <sup>a</sup>	2.37E-2	2.76E-2	11.93E-2	5.73E-2	5.73E-2 <sup>a</sup>	6.49E-2	13.39E-2	1.80E-2 <sup>a</sup>	1.81E-2	2.26E-2	12.33E-2
Standard deviation	60	2.30E-2	2.30E-2 <sup>a</sup>	2.60E-2	9.53E-2	5.35E-2 <sup>a</sup>	5.36E-2	5.76E-2	10.64E-2	1.68E-2 <sup>a</sup>	1.69E-2	2.06E-2	9.77E-2
Standard deviation	80	2.27E-2	2.27E-2 <sup>a</sup>	2.62E-2	8.19E-2	4.91E-2 <sup>a</sup>	4.92E-2	5.51E-2	9.00E-2	1.60E-2 <sup>a</sup>	1.61E-2	1.94E-2	8.33E-2

<sup>a</sup>Smallest value for a given data set and a given length of the local data series.

of these cases is what we call a ‘regional data set’ and is described in section 4.1. The parameters used to generate each data set are provided in section 5.2.

**4.1. Structure of a Regional Data Set**

[38] The data structure for each case has three levels corresponding to (1) the station level, (2) the hydrological region level, and (3) the regional data set level which is a collection of regions on which the studied methods will be evaluated by Monte Carlo simulation. The lowest level corresponds to the hydrological station scale. Each generated element at this level is represented by a set of physiological variables and a variable length observation record. The generated elements at the second level represent hydrological regions and are collections of stations among which one is designated as the target station. The length of the generated record at each station is randomly selected between 15 and 70, except at the target site where 80-years series are generated. At the third level, several regions are generated using the same bias and the same variance covariance matrix of the regional model.

**4.2. Generation Procedure**

[39] The procedure consists essentially in generating a triplet( $q_{T1}$ ,  $q_{T2}$ ,  $q_{T3}$ ) of ‘real’ quantities at each site, and then using them to compute the GEV parameters using the procedure described in Appendix A. This procedure takes advantage of the fact that, in the specific case of the GEV distribution, given the triplet of return periods ( $T_1$ ,  $T_2$ ,  $T_3$ ), there is a bijection between the triplet of parameters ( $\mu$ ,  $\sigma$ ,  $\xi$ ) and the triplet of quantiles ( $q_{T1}$ ,  $q_{T2}$ ,  $q_{T3}$ ). At non target sites, the quantiles ( $q_{T1}$ ,  $q_{T2}$ ,  $q_{T3}$ ) are generated using the following equation:

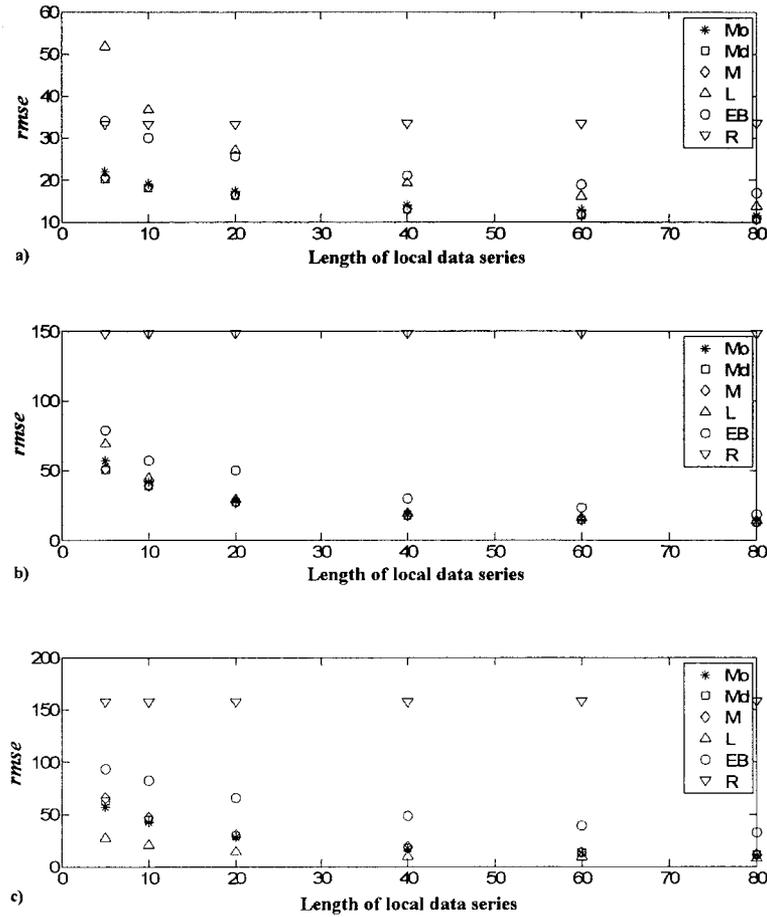
$$\log(q_T) = \begin{bmatrix} \log(q_{T1}) \\ \log(q_{T2}) \\ \log(q_{T3}) \end{bmatrix} = MVN(\beta x, \Sigma) \quad (18)$$

At target sites, ( $q_{T1}$ ,  $q_{T2}$ ,  $q_{T3}$ ) are generated following:

$$\log(q_T) = \begin{bmatrix} \log(q_{T1}) \\ \log(q_{T2}) \\ \log(q_{T3}) \end{bmatrix} = MVN((1 + b_i)\beta x, \Sigma) \quad (19)$$

where  $b_i$  is a bias parameter that ensures that the log linear regional model would be biased if used to estimate quantities at the target station. The reason for introducing  $b_i$  is that the regional model is always biased to some extent at the target site, since it is fitted with data from other sites. In a truly homogeneous region, the bias is null. In practice, there is always some moderate heterogeneity in hydrological regions and  $b_i$  was introduced to represent real life cases. The magnitude of the elements of  $\Sigma$  control the quality of the precision model: the lower the elements on the diagonal of  $\Sigma$ , the more precise the regional model would be. Note that in equation (19), the relative bias introduced through  $b_i$  affects all three quantiles, i.e. if the regional model overestimates  $q_T$ , then it will overestimate  $q_{T2}$  and  $q_{T3}$  in the same proportions. It seems reasonable that the relative errors of the regional model for the three quantiles would be the same. This constraint has an important implication: it preserves the ratios of quantile differences, thus the shape parameter (see Appendix A).

[40] To ensure that the simulations reproduce the complex relationships in the data set, we opted to use real



**Figure 9.** RMSE of the estimators of  $q_{10}$  according to the length of local data series: (a) first generated data set, (b) second generated data set, and (c) third generated data set.

field data for the vector  $\mathbf{x}$  of explanatory variables in equation (18). The field data should come from a known hydrological region, each column of  $\mathbf{x}$  representing a station inside that region. The vector of regression parameters  $\beta$  is computed from the same data set. The variance covariance matrix is computed using the following equation:

$$\Sigma = \alpha \begin{pmatrix} 1 & r_{T1,T2} & r_{T1,T3} \\ r_{T1,T2} & 1 & r_{T2,T3} \\ r_{T1,T3} & r_{T2,T3} & 1 \end{pmatrix} \quad (20)$$

In equation (20),  $\alpha$  is a parameter that allows to tune the quality of the regional regression and  $r_{T_i,T_j}$  is the correlation coefficient between regional estimates of  $q_{T_i}$  and  $q_{T_j}$  from the field data.

[41] Even though the same vector  $\mathbf{x}$  is used for each generated region and the same vector  $\beta$  is used for each generated region, the ‘true’ quantiles and parameters are different since the quantiles (and thus the parameters) are linked to the realizations of a random process (equations (18) and (19)). Each generated region is thus different from the others. Once  $\mathbf{x}$  and  $\beta$  are obtained, the simulation study proceeds using the following algorithm.

1. Choose the number  $M$  of regions to generate (the number of stations in a region is given by the number of rows of  $\mathbf{x}$ , plus one).

2. Choose the values of  $\alpha$  and  $b_r$  to set the characteristics of the regional model.

3. For each  $i \in \{1, \dots, M\}$ , generate the  $i$ th region following these steps.

3a. Choose a target station  $t \in \{1, \dots, n\}$ .

3b. For each  $k \in \{1, \dots, t-1, t+1, \dots, n\}$  generate  $(q_{T1}, q_{T2}, q_{T3})$  at the  $k$ th station using equation (18).

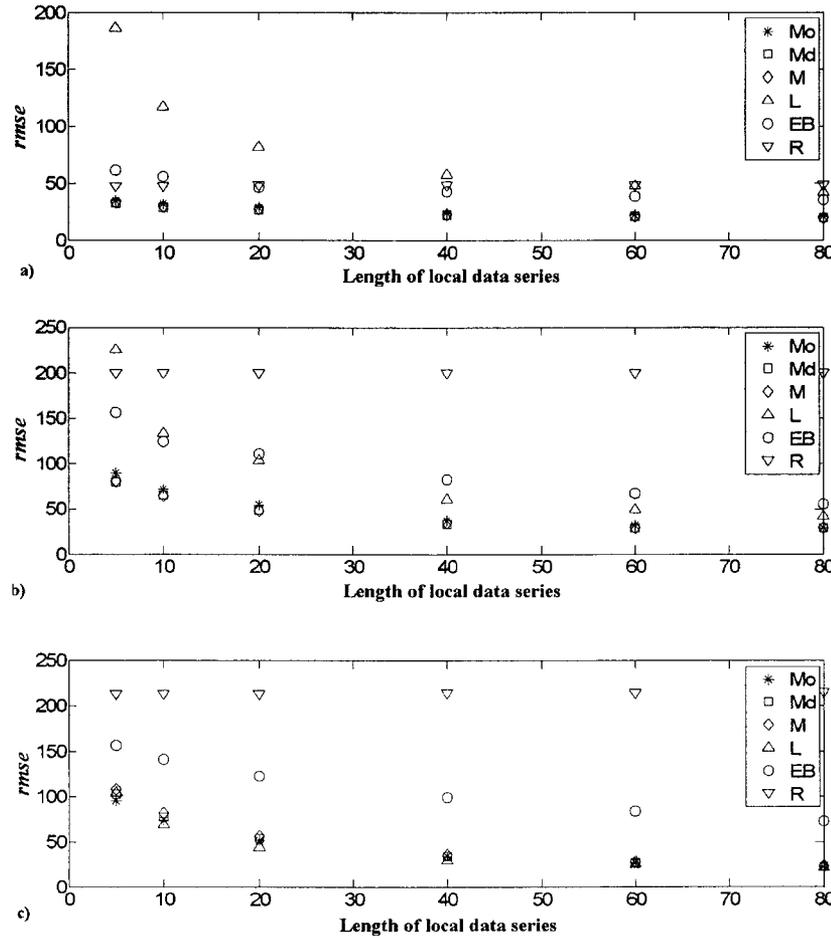
3c. Generate  $(q_{T1}, q_{T2}, q_{T3})$  at the  $k$ th station using equation (19).

3d. For each  $k \in \{1, \dots, n\}$ , compute the ‘true’ parameters  $\mu_k^i$ ,  $\sigma_k^i$  and  $\xi_k^i$  using the procedure given in Appendix A.

3e. For each  $k \in \{1, \dots, t-1, t+1, \dots, n\}$  pick a random number  $l$  between 15 and 70 and generate a  $l$ -year GEV sample using the simulated parameters  $\mu_k^i$ ,  $\sigma_k^i$  and  $\xi_k^i$ .

3f. Generate an 80-year GEV sample at the target site using  $\mu_t^i$ ,  $\sigma_t^i$  and  $\xi_t^i$ .

4. For each  $l \in \{5, 10, 20, 40, 80\}$ , consider  $l$  first generated values at the target sites as the recorded stream flows. Apply the different parameters and quantile estimation methods presented in this paper. To the regional



**Figure 10.** RMSE of the estimators of  $q_{100}$  according to the length of local data series: (a) first generated data set, (b) second generated data set, and (c) third generated data set.

data sets, and compute the performance criteria as function of  $l$ .

#### 4.3. Performance Measures

[42] The mode ( $Mo$ ), the median ( $Md$ ) and the mean ( $M$ ) of the posterior probability distribution of quantiles and parameters obtained by the parametric Bayesian method will be used as punctual estimators, along with the empirical Bayesian estimator ( $EB$ ), the regional estimator ( $R$ ) and the local estimator ( $L$ ). The performance of these five estimators will be assessed using the standard deviation ( $s$ ), the bias ( $b$ ) and the root-mean-square error (RMSE) defined by

$$s = \left( \frac{1}{n_s} \sum_{i=1}^{n_s} (\hat{\theta}_i - \mu_{\theta}(i))^2 \right)^{1/2} \quad (21)$$

$$b = \frac{1}{n_s} \sum_{i=1}^{n_s} (\hat{\theta}_i - \theta(i)) \quad (22)$$

$$\text{RMSE} = \sqrt{\frac{1}{n_s} \sum_{i=1}^{n_s} (\hat{\theta}_i - \theta(i))^2} \quad (23)$$

where  $n_s$  represents the number of samples,  $\theta$  the real value of the variable (quantile or parameter),  $\hat{\theta}_i$  its  $i$ th estimation

and  $\mu_{\theta} = \frac{1}{n_s} \sum_{i=1}^{n_s} \hat{\theta}_i$  the mean of the estimations. We shall also

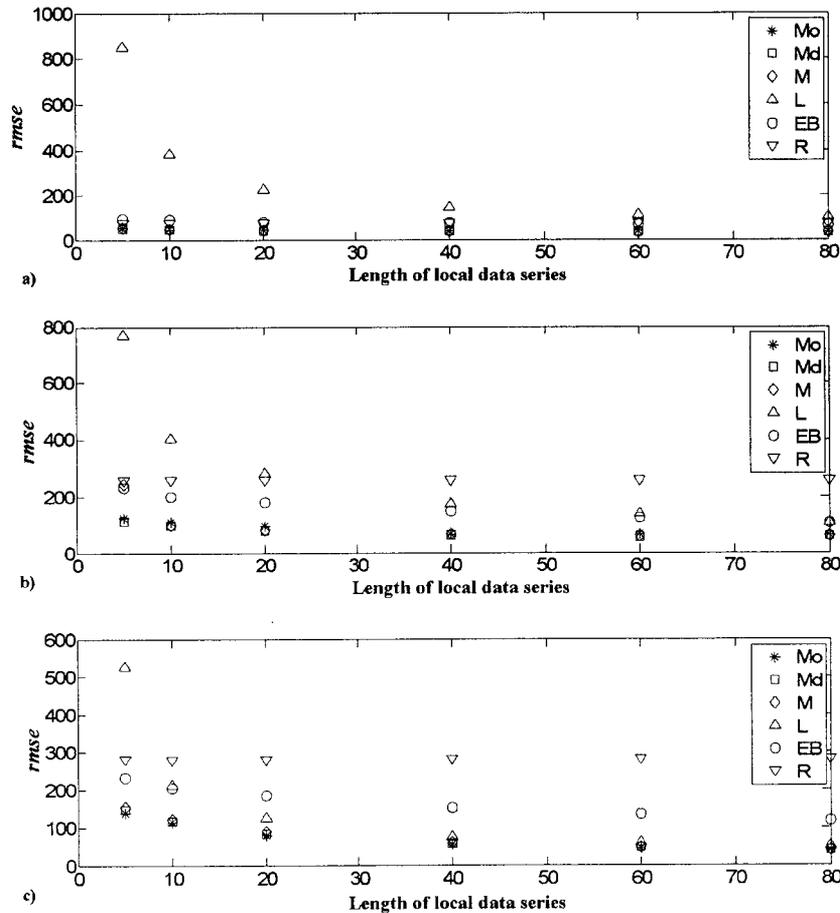
check whether the parameters  $\mu$ ,  $\sigma$  and  $\xi$  obtained with the complete Bayesian method are closer to the 'real' parameters than those estimated with the short series of data.

## 5. Application

[43] As mentioned in section 4.2, a real data set was required to extract realistic physiographical variables and compute reliable parameters for equations (18) and (19). The application consisted in selecting a hydrologic region, extracting physiographical variables, generating the remaining characteristics and then applying successively all the studied parameter and quantile estimation methodologies.

### 5.1. Field Data

[44] The data was extracted from a database of 168 hydrological stations provided by the Quebec Ministry of the Environment (Province of Quebec, Canada) and for which the following physiographic and meteorological variables were available: the catchment area, the percentage of the area covered by lakes, the mean slope of the catchment, the mean annual precipitation and the average annual accumulation of degree-days below zero.



**Figure 11.** RMSE of the estimators of  $q_{1000}$  according to the length of local data series: (a) first generated data set, (b) second generated data set, and (c) third generated data set.

[45] As the province of Quebec is commonly divided into thirteen hydrographic regions (Figure 1), a natural choice was the hydrographic region which contains the largest number of stations among those listed in the above mentioned database. Hydrographic region 05 was hence selected with 32 stations. These stations are illustrated in Figure 1, and their characteristics are listed in Table 1.

## 5.2. Characteristics of the Generated Regional Data Sets

[46] Three regional data sets corresponding to different characteristics of the log linear regional relationship were generated. Each regional data set contains 1000 regions ( $M = 1000$ ). The number of station in a given region is the same as in the Quebec 05 hydrographic region, from which the physiographic data is borrowed. The first data set is generated using an unbiased linear relationship between the explanatory variables and the logarithm of the quantiles ( $b_r = 0$ ), and a very low variance of the error component ( $\alpha = 0.10$ ). The second data set also uses an unbiased linear relationship between the explanatory variables and the logarithm of the quantiles, but with a larger variance ( $\alpha = 0.50$ ). The third data set is similar to the first

one, but a bias term is introduced at target sites ( $b_r = 100\%$ ). To provide an idea of the range of values that have been generated the local estimations of  $\mu$ ,  $\sigma$  and  $\xi$  as well as the regional estimations of  $q_{T1}$ ,  $q_{T2}$  and  $q_{T3}$  were computed at the target site in each region and in each regional data set. The histograms of the relative error of the regional estimation of  $q_{Ti}$ ,  $i = 1, \dots, 3$  are given in Figures 2a, 2b, and 2c for the first generated data set. The histograms of the local estimations of  $\mu$ ,  $\sigma$  and  $\xi$  are also provided in Figures 2d, 2e, and 2f. Similar histograms are provided for the second and third regional data sets are provided in Figures 3 and 4, respectively. Note that none of these histograms represent a normal distribution because of the logarithmic transformation in equations (18) and (19).

[47] The two values of  $\alpha$  (0.1 and 0.5) are consistent with observed values of the regional model error variance in Quebec hydrographic regions. For instance, the regional model error variance for the region 05 of Quebec was 0.0584 for  $q_{10}$ , 0.0814 for  $q_{100}$  and 0.1108 for  $q_{1000}$ . If we consider the set of all the hydrographic regions, the regional model error variance ranges from 0.0176 to 0.0951 for  $q_{10}$ , from 0.0361 to 0.1231 for  $q_{100}$ , and from 0.0534 to 0.2368

Table 5. RMSE, Bias, and Standard Deviation of the Estimators of  $q_{10}$

	<i>l</i>	First Generated Data Set						Second Generated Data Set						Third Generated Data Set					
		<i>M</i>	<i>Md</i>	<i>Mo</i>	<i>L</i>	<i>R</i>	EB	<i>M</i>	<i>Md</i>	<i>Mo</i>	<i>L</i>	<i>R</i>	EB	<i>M</i>	<i>Md</i>	<i>Mo</i>	<i>L</i>	<i>R</i>	EB
RMSE	5	20.47	20.17 <sup>a</sup>	21.90	51.75	33.16	33.83	50.87	50.42 <sup>a</sup>	57.18	68.80	148.01	78.68	65.76	62.56	57.13	27.15 <sup>a</sup>	157.29	93.17
RMSE	10	18.25	17.99 <sup>a</sup>	19.02	36.66	33.20	29.90	38.79 <sup>a</sup>	38.98	41.99	44.47	148.01	56.92	47.03	44.60	42.39	20.62 <sup>b</sup>	157.15	82.71
RMSE	20	16.42	16.33 <sup>a</sup>	17.19	27.02	33.26	25.47	26.81 <sup>a</sup>	26.98	28.26	29.44	148.01	49.95	30.38	29.29	28.04	14.22 <sup>a</sup>	157.17	65.97
RMSE	40	12.98	12.95 <sup>a</sup>	13.91	19.09	33.29	21.06	17.67	17.57 <sup>b</sup>	18.81	19.40	148.01	29.59	18.31	17.73	16.94	9.98 <sup>a</sup>	157.62	48.43
RMSE	60	11.68 <sup>a</sup>	11.70	12.83	16.08	33.38	18.84	14.28	14.28 <sup>a</sup>	15.14	15.96	148.01	23.00	13.74	13.41	13.50	8.85 <sup>a</sup>	157.94	38.61
RMSE	80	10.64	10.59 <sup>a</sup>	11.42	13.70	33.37	16.88	12.93 <sup>a</sup>	12.96	13.70	14.14	148.01	18.19	11.20	10.94	10.64	7.55 <sup>a</sup>	158.25	32.15
Bias	5	1.59	0.63	-0.70	-6.84	0.11 <sup>a</sup>	-8.70	1.75 <sup>a</sup>	-3.78	-10.65	-2.82	-11.49	-17.94	48.57	46.20	42.01	-4.39 <sup>a</sup>	115.33	42.64
Bias	10	1.52	0.80	-0.60	-2.27	0.24 <sup>a</sup>	-4.52	-0.09 <sup>a</sup>	-2.89	-7.47	-1.81	-11.49	-10.99	33.93	32.27	29.73	-0.75 <sup>a</sup>	115.18	36.02
Bias	20	1.14	0.60	-0.67	-0.89	0.25 <sup>a</sup>	-2.43	-0.67 <sup>a</sup>	-2.18	-4.93	-1.36	-11.49	-8.61	20.89	20.00	18.50	-0.30 <sup>a</sup>	115.17	27.57
Bias	40	0.52	0.16 <sup>a</sup>	-0.84	-0.77	0.25	-1.60	0.41	-0.39	-1.77	-0.24 <sup>a</sup>	-11.49	-4.56	11.95	11.47	10.50	-0.08 <sup>a</sup>	115.87	18.91
Bias	60	0.18	-0.11 <sup>a</sup>	-0.75	-0.84	0.22	-1.40	-0.12 <sup>a</sup>	-0.67	-1.86	-0.64	-11.49	-3.20	8.29	8.01	7.56	-0.13 <sup>a</sup>	116.32	14.14
Bias	80	-0.05 <sup>a</sup>	-0.25	-0.61	-0.73	0.22	-1.11	0.07 <sup>a</sup>	-0.32	-1.23	-0.46	-11.49	-2.42	6.50	6.28	5.76	-0.10 <sup>a</sup>	116.79	11.42
Standard deviation	5	20.41	20.16 <sup>a</sup>	21.89	51.30	33.16	32.69	50.84	50.28 <sup>a</sup>	56.18	68.75	147.56	76.60	44.33	42.18	38.71	26.79 <sup>a</sup>	106.96	82.84
Standard deviation	10	18.19	17.97 <sup>a</sup>	19.01	36.59	33.19	29.56	38.79 <sup>a</sup>	38.88	41.32	44.44	147.56	55.85	32.57	30.78	30.23	20.61 <sup>a</sup>	106.91	74.46
Standard deviation	20	16.38	16.32 <sup>a</sup>	17.18	27.01	33.26	25.35	26.80 <sup>a</sup>	26.89	27.83	29.41	147.56	49.21	22.05	21.40	21.07	14.22 <sup>a</sup>	106.96	59.93
Standard deviation	40	12.97	12.95 <sup>a</sup>	13.89	19.08	33.29	21.00	17.66	17.57 <sup>a</sup>	18.73	19.40	147.56	29.24	13.88	13.52	13.29	9.98 <sup>a</sup>	106.86	44.59
Standard deviation	60	11.68 <sup>a</sup>	11.70	12.81	16.05	33.38	18.79	14.28	14.26 <sup>a</sup>	15.03	15.95	147.56	22.78	10.95	10.75	11.19	8.85 <sup>a</sup>	106.84	35.92
Standard deviation	80	10.64	10.59 <sup>a</sup>	11.41	13.68	33.37	16.85	12.93 <sup>a</sup>	12.96	13.64	14.13	147.56	18.03	9.12	8.96	8.95	7.55 <sup>a</sup>	106.79	30.05

<sup>a</sup>Smallest value for a given data set and a given length of the local data series.

for  $q_{10}$ ; Thus the lowest value of  $\alpha$  (0.1) is in the range of observed values and can thus be considered as representing a homogeneous region. The upper value of  $\alpha$  (0.5) is largely above observed values and thus represents a heterogeneous region.

**5.3. MCMC Runs and Convergence Assessment**

[48] For each region, 5000 iterations of the MCMC algorithm were first run. Then, the Geweke [1992] convergence test is applied every 10000 iterations on the MCMC chains until convergence is successfully assessed. Furthermore, the parameters of the proposal distribution are dynamically changed in the course of the run to obtain an acceptance rate between 0.40 and 0.80, i.e., if the acceptance rate of the 100 last iterations is less than 0.4 the variance of the proposal distributions is reduced. Conversely, if the acceptance rate of the 100 last iterations is greater than 0.8, the variance of the proposal distributions is increased to better explore the parameter space. Examples of MCMC chains for the three quantiles  $q_{10}$ ,  $q_{100}$  and  $q_{1000}$  as well as for parameters  $\mu$ ,  $\sigma$  and  $\xi$  are provided in Figure 5. They are computed with the first region of the first generated data set and it is easy to visually check that the chains have reached their stationary distributions. All the other MCMC runs displayed similar characteristics. Once convergence successfully assessed for a given run, the last 10000 iterations were used to make the inference on the parameters  $\mu$ ,  $\sigma$  and  $\xi$  as well as the quantiles  $q_{10}$ ,  $q_{100}$  and  $q_{1000}$ .

**6. Results and Discussion**

[49] Once the simulations were performed, the effects of regional homogeneity and the effects of the length of the local data series on parameters and quantiles estimation were investigated.

**6.1. Effects on Parameter Estimation**

[50] The RMSE of the  $M$ ,  $Md$  and  $Mo$  parameter estimators is plotted as function of the length of the local data series and compared in Figures 6–8 to the RMSE of the local estimator ( $L$ ) for the three regional data sets. The RMSE, bias and standard deviation of these estimators are presented in Tables 2–4.

[51] It can be seen in Figure 8 as well as in Table 4 that the RMSE and the standard deviation of the shape parameter are much smaller when estimated with the parametric Bayesian approach than those obtained with the local estimator. This is true for all regional data sets and all lengths of data series. Since large return period quantile magnitudes are very sensitive to variations of  $\xi$ , this means that the parametric Bayesian method will lead to more stable estimations when the data series are short.

[52] The parametric Bayesian approach performs also better than the local estimation when estimating the location and scale parameters  $\mu$  and  $\sigma$  on the first generated data set: it leads to smaller RMSE and standard deviation for all values of  $l$  (Tables 2 and 3 and Figures 6a and 7a). The same conclusion can be drawn for the second generated data set (Tables 2 and 3 and Figures 6b and 7b) except that the improvement is less important. Because of the large bias of the regional model, the local estimator outperforms the parametric Bayesian estimator when estimating  $\mu$  and  $\sigma$  on

**Table 6.** RMSE, Bias, and Standard Deviation of the Estimators of  $q_{100}$

	$l$	First Generated Data Set						Second Generated Data Set						Third Generated Data Set					
		$M$	$Md$	$Mo$	$L$	$R$	EB	$M$	$Md$	$Mo$	$L$	$R$	EB	$M$	$Md$	$Mo$	$L$	$R$	EB
RMSE	5	32.76	32.14 <sup>a</sup>	34.33	186.20	47.93	61.60	80.87	79.64 <sup>a</sup>	89.42	225.31	199.94	155.81	107.74	102.01	95.33 <sup>a</sup>	104.48	213.52	155.61
RMSE	10	29.21	28.76 <sup>a</sup>	31.53	117.36	47.80	55.45	64.31 <sup>a</sup>	65.19	71.37	133.33	199.94	123.98	81.37	77.26	73.59	68.84 <sup>a</sup>	213.33	140.57
RMSE	20	27.01	26.84 <sup>a</sup>	28.76	82.00	48.04	46.40	47.93 <sup>a</sup>	48.35	53.78	103.02	199.94	110.53	55.80	53.75	51.43	44.44 <sup>a</sup>	213.35	122.33
RMSE	40	22.55	22.43 <sup>a</sup>	23.94	57.63	48.09	42.38	33.82	33.41 <sup>a</sup>	36.74	60.56	199.94	82.24	35.65	34.49	33.93	29.61 <sup>a</sup>	213.97	98.71
RMSE	60	20.84	20.80 <sup>a</sup>	22.14	47.34	48.23	38.47	28.85	28.63 <sup>a</sup>	31.82	48.77	199.94	66.75	27.57	26.78	26.95	24.60 <sup>a</sup>	214.40	83.41
RMSE	80	19.32	19.22 <sup>a</sup>	20.81	41.60	48.21	35.61	28.28	28.18 <sup>a</sup>	28.38	40.97	199.94	55.19	23.22	22.58	22.39	21.33 <sup>a</sup>	214.75	71.86
Bias	5	3.38	1.51	-1.35	17.39	-0.23 <sup>a</sup>	-18.20	3.61 <sup>a</sup>	-7.40	-21.87	16.43	-8.88	-41.31	78.46	74.27	67.80	12.15 <sup>a</sup>	157.18	79.48
Bias	10	2.69	1.39	-1.25	6.34	-0.03 <sup>a</sup>	-13.50	0.36 <sup>a</sup>	-5.39	-15.19	8.24	-8.88	-27.98	57.33	54.43	50.14	5.77 <sup>a</sup>	156.98	66.52
Bias	20	2.02	0.98	-1.28	2.49	0.01 <sup>a</sup>	-8.58	0.33 <sup>a</sup>	-3.37	-10.03	5.25	-8.88	-20.68	37.25	35.62	33.07	3.47 <sup>a</sup>	156.95	57.50
Bias	40	1.26	0.53	-1.02	0.64	0.04 <sup>a</sup>	-5.97	2.37	-0.24 <sup>a</sup>	-4.42	1.57	-8.88	-12.56	22.81	21.88	20.48	2.32 <sup>a</sup>	157.93	43.34
Bias	60	0.72	0.09	-1.38	-0.72	0.03 <sup>a</sup>	-4.71	2.02	-0.10 <sup>a</sup>	-3.07	0.56	-8.88	-8.88	16.80	16.18	15.41	1.58 <sup>a</sup>	158.53	34.84
Bias	80	0.37	-0.13	-1.02	-0.40	0.03 <sup>a</sup>	-3.50	1.70	-0.17	-3.26	-0.05 <sup>a</sup>	-8.88	-7.40	13.87	13.37	12.47	1.21 <sup>a</sup>	159.13	28.90
Standard deviation	5	32.58	32.11 <sup>a</sup>	34.31	185.39	47.93	58.85	80.79	79.30 <sup>a</sup>	86.70	224.71	199.74	150.23	73.83	69.92	67.02 <sup>a</sup>	103.77	144.52	133.78
Standard deviation	10	29.08	28.73 <sup>a</sup>	31.50	117.19	47.80	53.78	64.31 <sup>a</sup>	64.97	69.74	133.07	199.74	120.78	57.74	54.83	53.86 <sup>a</sup>	68.60	144.45	123.83
Standard deviation	20	26.93	26.82 <sup>a</sup>	28.73	81.96	48.04	45.59	47.93 <sup>a</sup>	48.24	52.84	102.88	199.74	108.58	41.54	40.26	39.39 <sup>a</sup>	44.30	144.52	107.97
Standard deviation	40	22.51	22.42 <sup>a</sup>	23.91	57.62	48.09	41.96	33.74	33.41 <sup>a</sup>	36.47	60.54	199.74	81.28	27.40	26.67 <sup>a</sup>	27.05	29.52	144.37	88.69
Standard deviation	60	20.83	20.80 <sup>a</sup>	22.10	47.33	48.23	38.18	28.78	28.63 <sup>a</sup>	31.67	48.76	199.74	66.16	21.86	21.34 <sup>a</sup>	22.12	24.55	144.35	75.79
Standard deviation	80	19.32	19.22 <sup>a</sup>	20.78	41.60	48.21	35.44	28.23	28.18 <sup>a</sup>	28.19	40.97	199.74	54.69	18.62	18.20 <sup>a</sup>	18.60	21.29	144.21	65.79

<sup>a</sup>Smallest value for a given data set and a given length of the local data series.

the third generated data set (Tables 2 and 3 and Figures 6c and 7c).

**6.2. Effects on Quantile Estimation**

[53] The RMSE of the  $M$ ,  $Md$  and  $Mo$  quantile estimators are compared in Figures 9 through 11 to the RMSE of the local, empirical Bayes and regional estimators for the three regional data sets. The RMSE, bias and standard deviations of these estimators are presented in Tables 5–7.

[54] Figure 9 and Table 5 show that overall, the best estimator (in terms of RMSE and standard deviation) for  $q_{10}$  on the first generated data set is  $Md$ , closely followed by  $M$  and  $Mo$ . Next comes EB, and then  $R$  or  $L$  depending of the length of the local data series.  $R$  is the worst estimator when the length of the local data series is larger than 10, but it is better than  $L$  when  $l = 5$  and  $l = 10$ . Depending on  $l$ ,  $M$  or  $Md$  take the first place when estimating  $q_{10}$  on the second generated data set, followed by  $L$ , EB and  $R$ . The improvement due to the use of the parametric Bayesian method instead of the local estimation method is smaller than in the case of the first generated data set. Finally, the  $L$  estimator turns to be the best with regard to all performance measures on the third data set.

[55] Similar conclusions can be drawn for the estimation of quantile  $q_{100}$  (Figure 10 and Table 6). The ranking of the different estimators remains the same but the parametric Bayesian approach seems to be more competitive than in the case of  $q_{10}$ . The improvement over  $L$  is larger (Figure 9b versus Figure 10b) for the second data set, and  $L$  hardly beats  $M$ ,  $Mo$  and  $Md$  when estimating  $q_{100}$  on the third generated data set (Figure 10c). The parametric Bayesian estimators become the bests for all data set when used to estimate  $q_{1000}$  (Figure 10 and Table 6). Results indicate that the proposed method becomes more and more efficient as the return period increases. This property makes it very attractive for design purposes where high return period quantiles are of interest.

[56] The reason for which the proposed approach performs better than the EB approach is that the latter does not account for the distribution of the local data series. EB makes the simplifying and often unverified assumption that the probability distributions of both regional and local quantile estimators are normal, which is not the case. This is true neither for the regional model (only the logarithm of the quantile is normal), nor for the local quantile estimator. The parametric Bayesian estimator does not make such limiting assumptions and the fact it leads to better result it is not surprising.

**6.3. Effect of Longer Local Data Series**

[57] It can be seen in Figures 6–11 as well as in Tables 2–7 that when the length of the local data series increases, the RMSE and the standard deviation of all quantile estimators but the regional one decrease. The bias decreases almost consistently, although a few cases arose were the bias increased. For instance, the reduction of the RMSE of quantile estimators on all data sets ranges from 29% to 41% for the local estimator (mean reduction: 34%), from 6% to 41% for the empirical Bayes estimator (mean reduction: 20%), and from 13% to 40% for the parametric Bayesian estimators (mean reduction: 19%) when the length of data series increases from 20 to 40 years.

[58] The reduction of RMSE due to the proposed Bayesian combination method is compared in Table 8 to the reduction

**Table 7.** RMSE, Bias, and Standard Deviation of the Estimators of  $q_{100}$

	<i>l</i>	First Generated Data Set						Second Generated Data Set						Third Generated Data Set					
		<i>M</i>	<i>Md</i>	<i>Mo</i>	<i>L</i>	<i>R</i>	EB	<i>M</i>	<i>Md</i>	<i>Mo</i>	<i>L</i>	<i>R</i>	EB	<i>M</i>	<i>Md</i>	<i>Mo</i>	<i>L</i>	<i>R</i>	EB
RMSE	5	51.40	49.87 <sup>a</sup>	51.19	850.55	73.35	92.42	242.44	111.62 <sup>a</sup>	122.65	769.44	258.18	230.42	154.71	146.59	137.67 <sup>a</sup>	526.48	281.60	232.76
RMSE	10	45.97	44.95 <sup>a</sup>	46.30	380.31	72.95	90.79	97.52	97.33 <sup>a</sup>	110.29	402.71	258.18	198.45	122.05	116.08	114.25 <sup>a</sup>	213.54	281.34	204.23
RMSE	20	42.75	42.23 <sup>a</sup>	43.93	225.34	73.43	78.93	81.17	80.32 <sup>a</sup>	93.81	280.00	258.18	178.34	88.22	84.84	80.64 <sup>a</sup>	125.18	281.36	184.64
RMSE	40	37.20	36.81 <sup>a</sup>	37.54	144.83	73.50	74.11	64.44	62.49 <sup>a</sup>	65.67	172.25	258.18	148.19	59.35	57.26	55.15 <sup>a</sup>	75.83	282.19	152.38
RMSE	60	35.50	35.23 <sup>a</sup>	36.55	112.63	73.72	67.07	60.14	57.96 <sup>a</sup>	65.25	137.66	258.18	124.81	47.47	45.92	43.84 <sup>a</sup>	59.47	282.76	133.42
RMSE	80	33.84	33.45 <sup>a</sup>	35.44	100.89	73.69	62.80	60.42	58.36 <sup>a</sup>	62.79	106.04	258.18	106.67	41.08	39.73	39.09 <sup>a</sup>	51.48	283.18	117.20
Bias	5	6.50	3.54	-0.65 <sup>a</sup>	197.57	1.40	-20.22	18.16	-8.74	-30.97	153.35	-4.34 <sup>a</sup>	-52.47	108.56	102.56	93.63 <sup>a</sup>	121.38	202.80	130.01
Bias	10	5.15	3.13	0.25 <sup>a</sup>	61.87	1.65	-22.37	6.10	-5.86	-23.18	68.63	-4.34 <sup>a</sup>	-42.02	82.00	77.84	72.87	38.36 <sup>a</sup>	202.55	98.56
Bias	20	4.14	2.49	-0.36 <sup>a</sup>	24.33	1.76	-15.86	5.71	-2.36 <sup>a</sup>	-14.76	41.93	-4.34	-32.43	55.73	53.22	49.14	19.43 <sup>a</sup>	202.49	86.57
Bias	40	3.23	1.96	-1.02 <sup>a</sup>	10.92	1.81	-11.51	7.62	1.02 <sup>a</sup>	-7.53	13.02	-4.34	-19.01	36.11	34.57	32.19	10.67 <sup>a</sup>	203.76	66.04
Bias	60	2.48	1.34	-0.75 <sup>a</sup>	4.47	1.80	-8.74	7.75	1.96 <sup>a</sup>	-6.96	7.99	-4.34	-13.27	27.84	26.75	24.70	7.34 <sup>a</sup>	204.55	54.43
Bias	80	2.06	1.10	-0.53 <sup>a</sup>	4.30	1.80	-6.05	6.45	1.30 <sup>a</sup>	-7.04	4.91	-4.34	-11.34	23.73	22.78	21.60	5.42 <sup>a</sup>	205.29	45.72
Standard deviation	5	50.99	49.75 <sup>a</sup>	51.18	827.29	73.34	90.18	241.76	111.27 <sup>a</sup>	118.67	754.00	258.14	224.37	110.23	104.74	100.92 <sup>a</sup>	512.30	195.37	193.06
Standard deviation	10	45.68	44.84 <sup>a</sup>	46.29	375.25	72.93	87.99	97.33	97.16 <sup>a</sup>	107.82	396.82	258.14	193.95	90.39	86.12 <sup>a</sup>	87.99	210.06	195.26	178.87
Standard deviation	20	42.55	42.15 <sup>a</sup>	43.93	224.02	73.41	77.32	80.97	80.29 <sup>a</sup>	92.64	276.84	258.14	175.37	68.38	66.08	63.93 <sup>a</sup>	123.67	195.35	163.08
Standard deviation	40	37.06	36.76 <sup>a</sup>	37.52	144.42	73.48	73.21	63.98	62.49 <sup>a</sup>	65.24	171.76	258.14	146.96	47.10	45.65	44.78 <sup>a</sup>	75.08	195.22	137.33
Standard deviation	60	35.42	35.20 <sup>a</sup>	36.54	112.55	73.70	66.50	59.64	57.93 <sup>a</sup>	64.88	137.43	258.14	124.11	38.45	37.33	36.21 <sup>a</sup>	59.02	195.22	121.81
Standard deviation	80	33.78	33.44 <sup>a</sup>	35.44	100.80	73.66	62.50	60.07	58.34 <sup>a</sup>	62.40	105.92	258.14	106.07	33.53	32.55 <sup>a</sup>	32.58	51.19	195.07	107.92

<sup>a</sup>Smallest value for a given data set and a given length of the local data series.

of RMSE due to the use of the 40-year data series instead of the 20-year data series. It can be seen that, for the first data set, the use of the *Md* quantile estimator always leads to a higher average reduction of the RMSE than the use of the 40-year data series instead of the 20-year data series. The same conclusion can be drawn for the second data set, but only for  $q_{100}$  and  $q_{1000}$ . An interesting remark is that the parametric Bayesian method is helpful when estimating  $q_{1000}$  on the third data set, but not as much as doubling the length of the local data series. It means that the Bayesian method for combining at-site and regional information cannot and should not be considered as a substitute to a sustained intensive hydrological monitoring program. Quite the opposite: the application of the proposed Bayesian information combination method is only possible because of the availability of a reasonably good and dense regional network of stations with a good record of information. In fact, this result points out the importance of maintaining a good hydrometeorological network, as the available record can be used not only for at site frequency analysis but also for the estimation at other sites, even ungauged or shortly gauged ones.

**6.4. Sensitivity to Regional Information**

[59] As pointed out in section 6.1, the ability of the proposed methodology to correctly estimate the location and scale parameter decreases when a nonnull relative bias is introduced in the regional model. This relative bias does not seem to affect its ability to correctly estimate the shape parameter. The reason for this is that the relative bias introduced through  $b_r$  affects all three quantiles in the same proportions. It is shown in Appendix A that the shape parameter is function of a ratio of quantile differences and thus should not be affected by  $b_r$ . Whether this constraint in the generation scheme is reasonable or not is a matter of judgment. The authors' experience has shown that when using the log linear regional regression model, quantiles of different return periods tend to be biased in the same direction (downward or upward) and the magnitude of their biases are comparable.

[60] A simple sensitivity analysis of the method to differences in the relative biases for different return periods was performed. Equation (19) was slightly modified to affect different relatives biases ( $b_{r1}$ ,  $b_{r2}$ ,  $b_{r3}$ ) in the regional model of quantiles ( $q_{T1}$ ,  $q_{T2}$ ,  $q_{T3}$ ). For illustration purposes, we considered  $b_{r1} = b_{r2} = 0$  and allowed  $b_{r3}$  to vary from 0 to 1 with increments of 0.1. For each value of ( $b_{r1}$ ,  $b_{r2}$ ,  $b_{r3}$ ), a regional data set was generated following the procedure described in section 4 and the following quantities were computed: (1) the mean difference  $\Delta\mu$  between location parameter at target sites and location parameter at nontarget sites, (2) the mean difference  $\Delta\sigma$  between scale parameter at target sites and scale parameter at nontarget sites, (3) the mean difference  $\Delta\sqrt{\xi}$  between shape parameter at target sites and shape parameter at nontarget sites, and (4) estimations of  $q_{10}$ ,  $q_{100}$  and  $q_{1000}$  using the *Md* estimator.  $\Delta\mu$  is computed as follows:

$$\Delta\mu = \frac{1}{M} \sum_{i=1}^M \left( \mu_i^t - \frac{1}{(n-1)} \sum_{j=1, j \neq i}^n \mu_j^t \right) \quad (24)$$

**Table 8.** Percentage of Reduction of RMSE due to the Change in the Length of Data Series (From 20 years to 40 years) or the Application of Bayesian Combination Methods

	First Generated Data Set				Second Generated Data Set				Third Generated Data Set			
	<i>M</i>	<i>Md</i>	<i>Mo</i>	<i>S</i> <sup>a</sup>	<i>M</i>	<i>Md</i>	<i>Mo</i>	<i>S</i> <sup>a</sup>	<i>M</i>	<i>Md</i>	<i>Mo</i>	<i>S</i> <sup>a</sup>
Q10	39.23%	39.58%	36.38%	29.34%	8.94%	8.35%	4.01%	34.09%	-113.57%	-105.95%	-97.15%	29.81%
Q100	67.06%	67.26%	64.93%	29.72%	53.47%	53.06%	47.79%	41.21%	-25.57%	-20.96%	-15.73%	33.37%
Q1000	81.03%	81.26%	80.50%	35.73%	71.01%	71.31%	66.50%	38.48%	29.53%	32.22%	35.59%	39.42%

<sup>a</sup>S = Switching from *l* = 20 to *l* = 40.

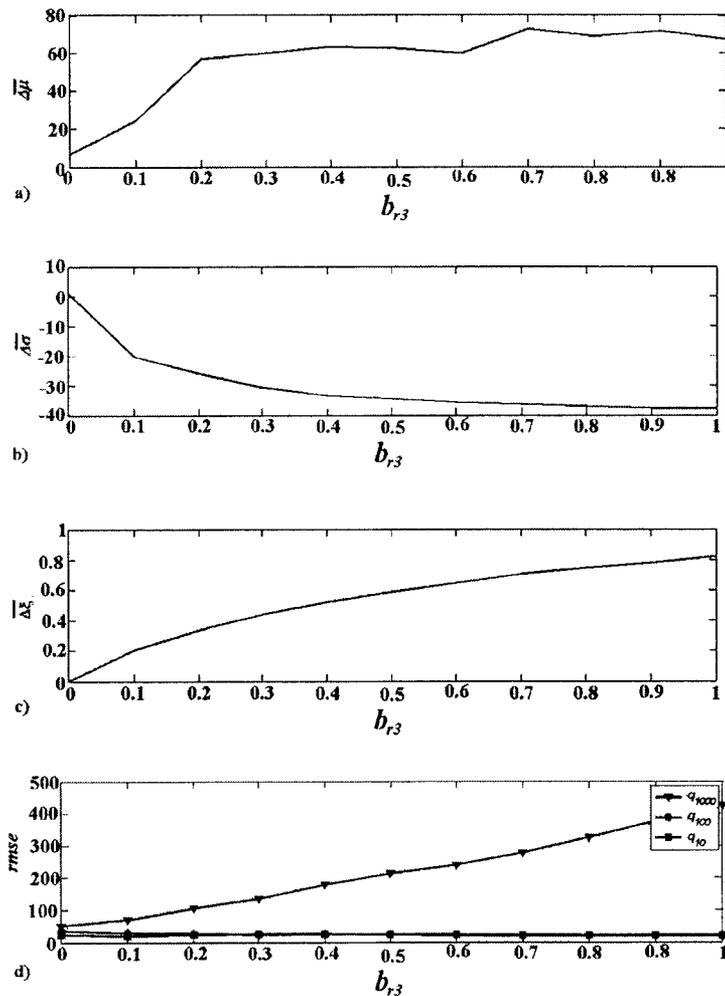
$\overline{\Delta\sigma}$  and  $\overline{\Delta\xi}$  are computed using the same procedure. Given a regional data set,  $\overline{\Delta\mu}$ ,  $\overline{\Delta\sigma}$  and  $\overline{\Delta\xi}$  are measures of how the parameters at target sites differ from the parameters in their respective regions.

[61] The results are plotted in Figure 12 and allow to draw the following conclusions.

[62] 1. As expected, regional heterogeneity increases as  $b_{r3}$  becomes very different from  $b_{r1}$  and  $b_{r2}$  (i.e.,  $\overline{\Delta\mu}$ ,

$\overline{\Delta\sigma}$  and  $\overline{\Delta\xi}$  become significantly different from zero).  $\overline{\Delta\mu}$  and  $\overline{\Delta\xi}$  increase, while  $\overline{\Delta\sigma}$  decrease.

[63] 2. As  $b_{r3}$  (and thus regional heterogeneity) increases, the RMSE of the *Md* estimator of  $q_{1000}$  increases, which means that the proposed method becomes less efficient for this particular quantile. The RMSE of the estimator of  $q_{10}$  and  $q_{100}$  do not seem to be affected. The best performance corresponds to  $b_{r1} = b_{r2} = b_{r3} = 0$ .



**Figure 12.** Sensibility analysis of the statistical parameters of the generated samples and the performances of the proposed methodology to the bias parameter  $b_{r3}$  ( $b_{r1} = b_{r2} = 0$ ): (a)  $\overline{\Delta\mu}$ , (b)  $\overline{\Delta\sigma}$ , (c)  $\overline{\Delta\xi}$ , and (d) RMSE of the *Md* estimator of  $q_{10}$ ,  $q_{100}$ , and  $q_{1000}$ .

[64] Indeed, this sensitivity analysis does not cover all the range of possible configurations of  $b_{r1}$ ,  $b_{r2}$ ,  $b_{r3}$ , and further investigation is desirable. However, the results strongly suggest that the methodology may be counterproductive at sites that are very different from the regional mean. This potential problem should be circumvented by a careful choice of the neighborhood delineation method.

### 6.5. Generalization to Other Extreme Value Distributions

[65] In the specification of the prior, only the Jacobian  $J$  (equation (15)) depends of the distribution. Thus its application to other extreme value distributions is straightforward if an expression of  $J$  can be derived for the new distribution. The MCMC algorithm will also need to be adapted to the target distribution. Other analytical expressions for  $\Delta q_{T_i}$  may also be used provided that the expression of  $J$  does not take null values in the parameter space.

## 7. Conclusions

[66] A parametric Bayesian methodology to combine local and regional information in order to improve the estimation of flood quantiles is presented. The methodology is validated on three simulated data sets representing different levels of regional homogeneity. In this method, the prior information is specified using multiple regression on quantiles and quantile differences. The developments are made with the generalized extreme value distribution but guidelines are provided for its extension to other distributions. The proposed method relaxes the assumption of the local quantile probability distribution and can be applied to very short data series. It stabilizes the estimation of the GEV shape parameter and improves significantly the estimation of the parameters and the quantiles when relatively short series are used. The method was shown to be superior in terms of RMSE to the local and regional estimators, and to the empirical Bayesian estimator used by *Kuczera* [1982]. On two out of the three simulated data sets, it was shown that the improvement in quantile estimation due to the use of the parametric Bayesian approach is at least equivalent to that obtained with the use of at-site series that are twice as long. The method presented in this paper is thus a promising approach for the estimation of quantiles at sites with short to medium length flood records.

### Appendix A: Computation of $\mu$ , $\sigma$ , and $\xi$ From $q_{T_1}$ , $q_{T_2}$ , and $q_{T_3}$

[67] These equations allow to compute  $\mu$ ,  $\sigma$ , and  $\xi$  given  $\Delta q_{T_1}$ ,  $\Delta q_{T_2}$  and  $\Delta q_{T_3}$ . From equations (8) and (9) we have

$$\frac{\Delta q_{T_3}}{\Delta q_{T_2}} = \frac{q_{T_3} - q_{T_1}}{q_{T_2} - q_{T_1}} = \frac{((- \log(1 - p_3))^{-\xi} - (- \log(1 - p_1))^{-\xi})}{((- \log(1 - p_2))^{-\xi} - (- \log(1 - p_1))^{-\xi})} = g(\xi | T_1, T_2, T_3) \quad (A1)$$

If  $g$  is a monotonic function of  $\xi$ ,  $g^{-1}$  exists and we have:

$$\xi = g^{-1}(q_{T_1}, q_{T_2}, q_{T_3} | T_1, T_2, T_3) \quad (A2)$$

$$\sigma = \frac{g^{-1}(q_{T_1}, q_{T_2}, q_{T_3} | T_1, T_2, T_3)(q_{T_3} - q_{T_1})}{((- \log(1 - p_3))^{-\xi} - (- \log(1 - p_1))^{-\xi})} \quad (A3)$$

$$\mu = q_{T_1} + (- \log(1 - p_1))^{-\xi} \frac{\sigma}{\xi} \quad (A4)$$

A simple plot of  $g$  versus  $\xi$  allows to confirm that  $g$  is monotonic for  $T_1 = 10$ ,  $T_2 = 100$  and  $T_3 = 1000$ .

### Notation

$\alpha$	parameters that allows to tune the precision of the regional model.
$\tilde{\beta}$	matrix of regression coefficients.
$\beta^{(i)}$	$i$ th row of $\beta$ .
$\Delta\mu$	mean difference between location parameter at target sites and location parameter at nontarget sites.
$\overline{\Delta\sigma}$	mean difference between scale parameter at target sites and location parameter at nontarget sites.
$\overline{\Delta\xi}$	mean difference between shape parameter at target sites and shape parameter at nontarget sites.
$b_r$	common bias parameter for $q_{T_1}$ , $q_{T_2}$ , $q_{T_3}$ .
$b_{r1}$ (resp. $b_{r2}$ , $b_{r3}$ )	bias parameter for $q_{T_1}$ (resp. $q_{T_2}$ , $q_{T_3}$ ).
$A_k$	value of the $k$ th physiographic or meteorological variable at the site of interest.
$EB$	empirical Bayes estimator.
$f(\mathbf{x} \theta)$	likelihood of the observations.
$L$	local estimator.
$M$	mean of the quantile or parameter posterior probability density.
$Med$	median of the quantile or parameter posterior probability density.
$Mo$	mode of the quantile or parameter posterior probability density.
$\mu$	location parameter of the GEV distribution.
$n$	sample size.
$n_s$	number of samples.
$p$	exceedance probability.
$\pi(\theta)$	prior probability density of the parameters.
$p(\theta \mathbf{x})$	posterior probability density of the parameters given the data.
$q_T$	$T$ -year flood.
$\Delta q_{T_1}$	$T_1$ -year flood.
$\Delta q_{T_i}$ , $i \geq 2$	difference between the $T_i$ -year flood and the $T_{i-1}$ -year flood.
$\hat{q}_T^{(L)}$	local estimation of the $T$ -year flood.
$\hat{q}_T^{(R)}$	regional estimation of the $T$ -year flood.
$R$	regional estimator.
$\Sigma$	variance-covariance matrix.
$\sigma_L$	standard deviation of the local estimation of the $T$ -year flood.

$\sigma_R$	standard deviation of the regional estimation of the T-year flood.
T	return period.
$\theta = (\mu, \sigma, \xi)$	parameters vector.
$\theta_i$	$i$ th estimation of the parameters vector.
$\mathbf{x}$	vector of observed data.
$\xi$	shape parameter of the GEV distribution.

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